



MICROCHIP

MASTERS Conference

1538-TCP2

*Designing Embedded TCP/IP
Monitor and Control*

Lab Manual

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Designing Embedded TCP/IP Monitor and Control



Lab Background/Flow, Solutions & Symbols:



Exercise Background and Flow:

Many embedded applications can be functionally enhanced if the designer includes the ability to access the system via the existing internet infrastructure. This concept was the focus of a webinar series, available on www.microchip.com/ethernet, that discusses adding Ethernet networking capability to a soda vending machine. That webinar series was the basis for developing this class and the 6 associated labs.

The user can choose one of 3 MCU platforms: 1) PIC18F, 2) PIC24F or 3) PIC32MX. Three MAC/PHY options are also available in the class. The PIC18F, via the PICDEM.net 2 board offers an integrated MAC/PHY or an external ENC28J60. The latter two offer one of three MAC/PHYs: ENC28J60 10Mbps, ENC624J600 10/100 Mbps, or MRF24WB0 wireless 1-2Mbps all via the Ethernet PICTail Plus modules. This choice is facilitated in the source files via *#if defines* shown in HardwareProfile.h header file.

Lab1-Join the Network-starts by using a demo application from the Microchip TCPIP stack distribution then utilizes the *TCPIPConfig* utility to set the development board up for the balance of the labs. Completion of this lab is required as the board's assigned MAC address and user-specified board name is copied to the subsequent labs files via the *Replicate HWConfig.bat* routine via the *TCPIPConfig.h* file.

Lab 2 is an exercise in designing an business card image on a HTML/CSS web page. Since this is a practice exercise the files are erased during subsequent labs. However, the user is given modifiable vending machine web pages to use for Labs 3 thru 6. These labs steer the user thru the process of integrating the vending machine application code with the TCP/IP stack, removing blocking code for maximum performance, and customizing for monitoring and controlling remote apps.

All the files used in these exercises have been loaded into the C:\RTC\COM4201\ directories along with the most recent version of the Microchip released TCP/IP stack. When newer stacks are web-downloaded, they are stored in a C:\Microchip Solutions folder during normal install. The applications used in this class are available in the most recent stack versions.



Solutions:

All but Lab 1 have solution projects available in their respective folders. However, for some labs just compiling the MCU solution is not adequate to complete the exercise. When using a solution workspace and it's associated completed firmware entries refer to the enclosed table for a starting point to complete the exercise.

Solution Steps

Lab 3:	Step 8
Lab 4:	Step 6
Lab 5:	Step 14
Lab 6:	Step 3



Code Analysis-HardwareProfile.h

Each compiler, facilitated by the HardwareProfile.h file and partially shown below, can determine the Microchip development platform used based on the compiler and part selected within the MPLAB project. Unique versions of this file are needed to differentiate between the MAC/PHY choices in the class. This is handled by TCPIP HWConfig.bat in Lab 1.

HardwareProfile.h



```
// Choose which hardware profile to compile for here. See
// the hardware profiles below for meaning of various options.
#define PICDEMNET2
#define HPC_EXPLORER
#define PICDEMZ
#define PIC24FJ64GA004_PIM // Explorer 16, but with the PIC24FJ64GA004 ...
#define EXPLORER_16 // PIC24FJ128GA010, PIC24HJ256GP610, ...
#define DSPICDEM11
#define DSPICDEMNET1 // Not currently supported, wrong Ethernet ...
#define DSPICDEMNET2 // Not currently supported, wrong Ethernet ...
#define YOUR_BOARD

// If no hardware profiles are defined, assume that we are using
// a Microchip demo board and try to auto-select the correct profile
// based on processor selected in MPLAB
#if !defined(PICDEMNET2) && !defined(HPC_EXPLORER) && !defined(PICDEMZ) && ...
    #if defined(__18F97J60) || defined(_18F97J60)
        #define PICDEMNET2
    #elif defined(__18F67J60) || defined(_18F67J60)
        #define INTERNET_RADIO
    #elif defined(__18F8722) || defined(_18F87J10) || defined(_18F8722) ...
        #define HPC_EXPLORER
```



Symbols



Helpful information for completing the lab2



BACKGROUND and PURPOSE of the Lab



PC configuration for the lab.



1 Procedural Commands to be executed



Sections of Ansi-C code



Sections of HTML/CSS code



Target results of the lab



Code Analysis and Conclusions of the lab



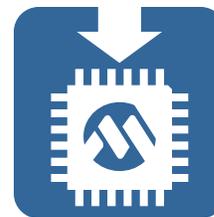
Cautions or warnings about frequent mistakes

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Lab Exercise 1

Join the Network



? Purpose

Before a device can be connected to a network, it needs a unique host name and MAC address. This ensures that the device can communicate independently with other network nodes, and prevents duplicate addresses on the network.

In this first lab, the **TCPIPConfig Wizard** will be used to configure a unique address for your development hardware.

These changes will be written to a configuration file named `TCPIPConfig.h` that is included in the project file, and will be compiled into the `COM4201 WiFi Demo App` project. To finish the lab, you will upload a set of example web pages and test the network connection.

☑ Requirements

Software: TCPIPConfig Wizard from 1538 Lab Build Installer v1.536
Environment: MPLAB[®] IDE 8.60 or later or X, 1538 Lab Build Installer 1.536
C Compiler: MPLAB C18 v3.38 or later, C30 v3.30 or later, or C32 v1.12 or later
H/W Tools: PIC18F: PICDEM.net[™] 2, or
 PIC24FFJ128GA010 PIM: Explorer 16 w/ 10Mbps, 10/100Mbps PICtail[™] Plus or MRF24WB0 or
 PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10Mbps, 10/100Mbps PICtail[™] Plus or MRF24WB0
 AND MPLAB Real ICE[™], MPLAB ICD3
 AND DHCP Enabled Router (wired or wireless)
Lab Files: C:\Masters\1538\Lab1...

🎯 Objectives

- Configure the lab class hardware platform and ensure it is connected to the local LAN.
- Use the TCPIP Config Utility to make specify the hardware configuration.

! Procedures

- 1 If you have a previous MPLAB project open, you must first close it by selecting from the menu:
File ▶ Close Workspace

Confirm the following directory/folder is used during the utility processing:



Project Directory:

C:\Masters\1538\Lab1*

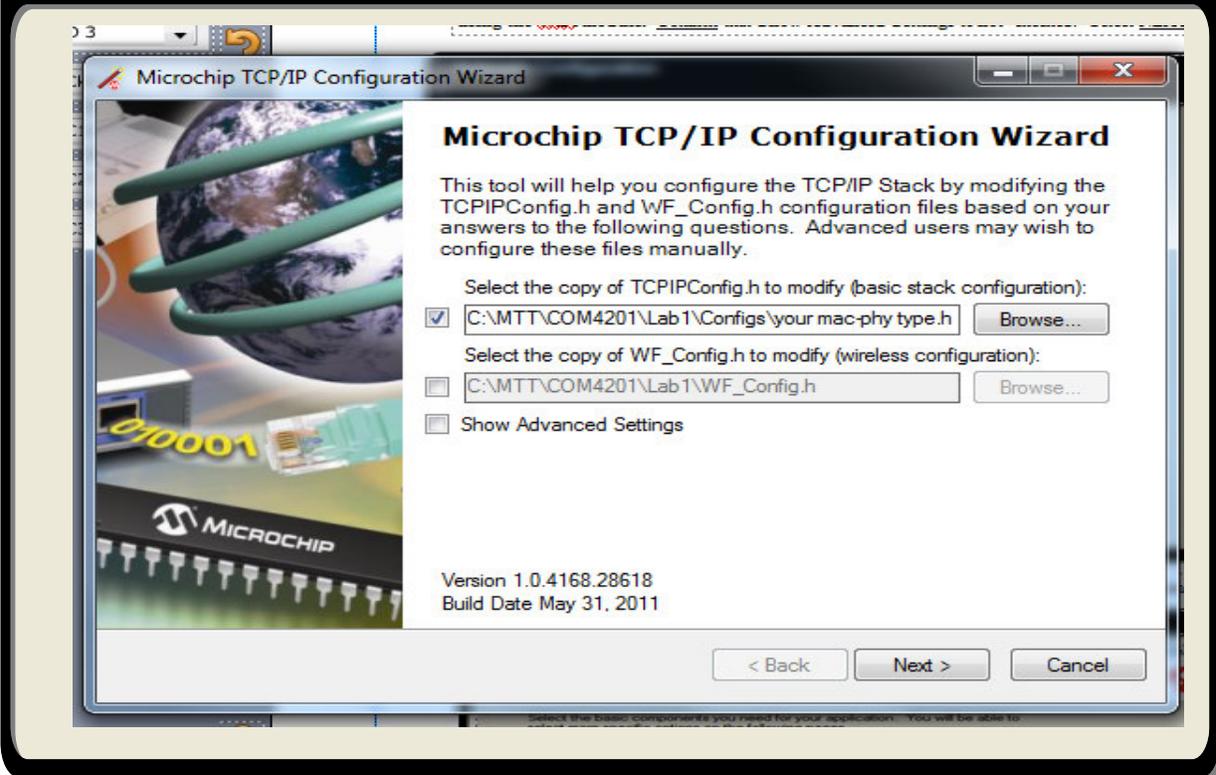
2

Launch the **TCPIP Config Wizard** to modify the TCPIPConfig.h.

Start ▶ Programs ▶ Microchip ▶ 1538 ▶ TCPIPConfig Wizard

Browse to **ENSURE** the Lab1\Configs directory shown below. Check the **CONFIGURE WIRELESS SETTINGS** if using the WiFi module. **Confirm** that **Show Advanced Settings** is **not** checked. Select **NEXT**.

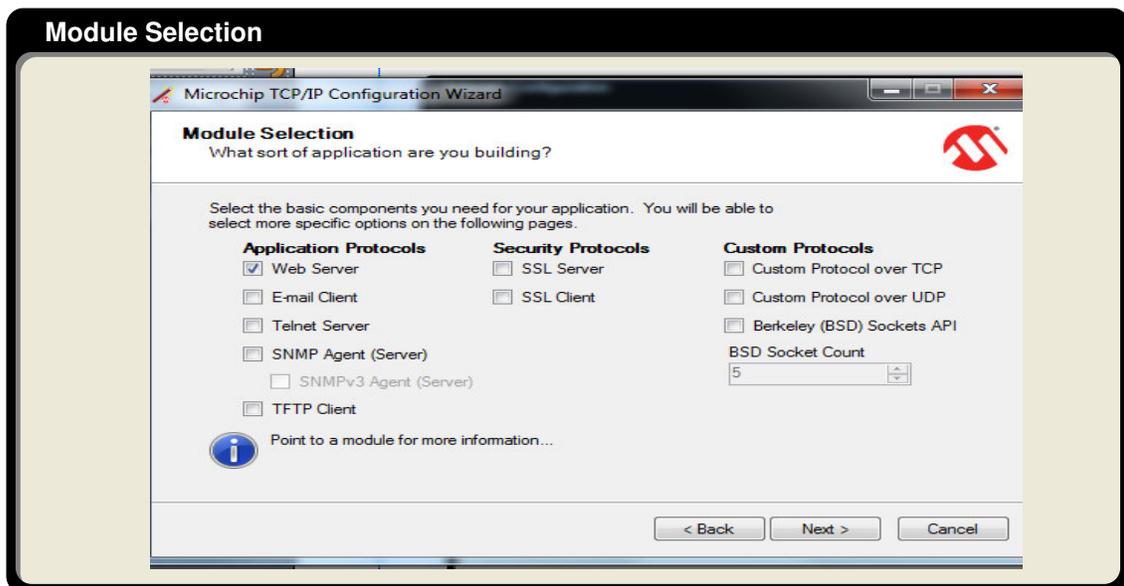
Network Configuration



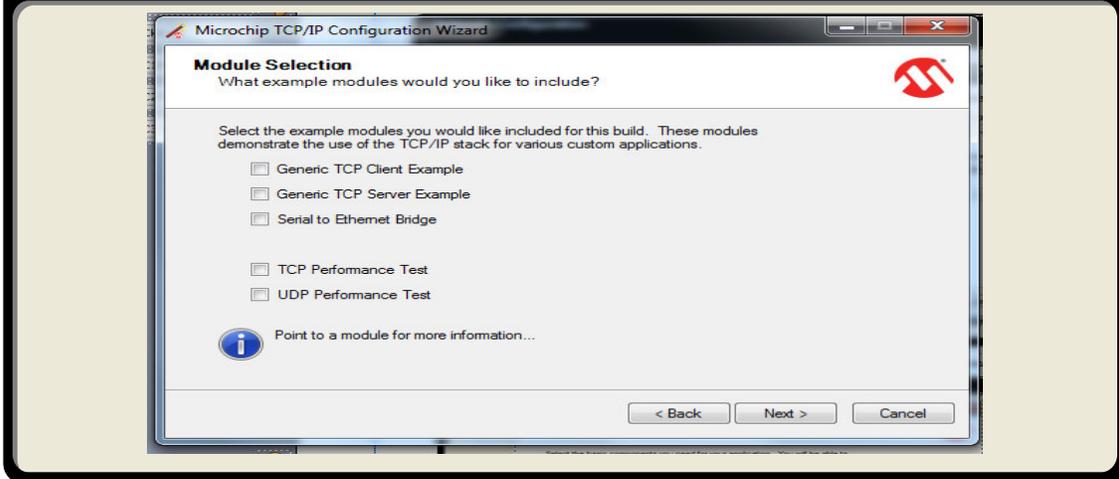
3

Ensure only the Web Server box is checked in the next two screens-Module Selection and Example Modules:

Module Selection



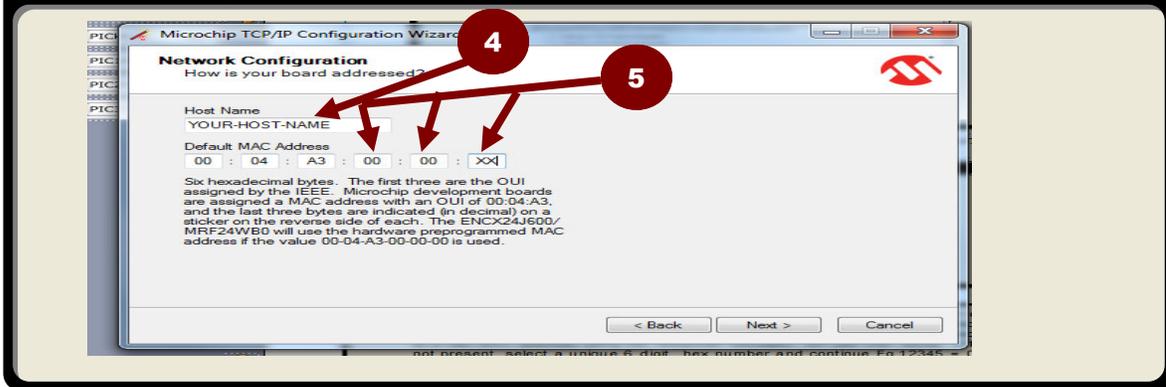
Example Modules



4

Define and enter a unique host name for your board on the NETWORK CONFIGURATION screen shown below. The name must be 15 characters or less, and cannot contain \ / : * ? " ; |

Network Configuration



Microchip assigned Ethernet MAC address decimal numbers are labeled on the wired 10Mbps PICTail Plus module or on the back of the PICDEM.net 2 development board. When using either of these, step 5 will require you to convert the Ethernet decimal number to a hex MAC address using the Windows calculator, left pad with zeros. If the number is not present, select a unique 6 digit hex number and continue. Eg. 12345 = 00:30:39 hex. 10/100Mbps PICTail and MRF24WB0 have preprogrammed MAC addresses, so click NEXT thru step 5.

5

If using PICDEM.net 2 or 10Mbps PicTail plus module, **Enter** the last 3 bytes of the MAC address field, in hex corresponding to the Ethernet serial decimal number printed on the label. If using the 10/100 PICTail Plus or the ZG2100, ensure that the last 3 hexadecimal digits are 00-00-00.

For wired configurations with the ENC28J60 or ENCx24J600

Click **Next** thru the following screens, and click **Finish** to complete the session.

[Skip to STEP 6](#) to continue the configuration process.

For wireless configurations using MRF24WB0 PICtail Plus Module:

Check the appropriate boxes for the regional configurations in the 2 screens below:

Click **Next** thru the following screens (no Security, no Web page change, no MPFS image change), until

Click **Finish** to complete the utility session.

Continue to Step 6 to continue the configuration process.

Network Configuration

Network Configuration

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6

Execute the batch script to copy TCPIP configuration just completed to all of the lab and lab solution project folders for use later in the class.

[Start](#) ▶ [Programs](#) ▶ [Microchip](#) ▶ [1538](#) ▶ [Replicate TCPIPCONFIG-HeaderFile.bat](#)



C:\Masters\1538\Lab1\Lab1-C**_***_***

7

[MPLAB File](#) ▶ [Open Project](#)



Lab1-C18-PICDN2-ETH97.X for the PICDEM.net 2 with internal MAC/PHY setup

Lab1-C18-PICDN2-MRF24W.X for the PICDEM.net 2 with Wireless MAC/PHY setup

Lab1-C30-EXP16-ENC28.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10Mbps module

Lab1-C30-EXP16-ENC624.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10/100Mbps module

Lab1-C30-EXP16-MRF24WB.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with WIFI module

Lab1-C32-EXP16-ENC28.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10Mbps module

Lab1-C32-EXP16-ENC624.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10/100Mbps module

Lab1-C32-EXP16-MRF24WB.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with WIFI module

8



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM



About Network Settings

The demo application stores network configuration settings in EEPROM, so settings stored in the project file are only loaded when EEPROM data is not present. Procedure #11 is only required when new network settings are configured for the project. **THIS ONLY NEEDS TO BE COMPLETED AFTER PROGRAMMING IN LAB1.**

9

Confirm a new IP address from the Router appears on the LCD, something besides 169.254...
Clear the on-board EEPROM by:

1. Hold the right-most pushbutton down (S5 on PICDEM.net 2, S4 on Explorer 16)
2. Press and release the /MCLR button (S1 on PICDEM.net 2, S1 on Explorer 16)
3. Continue holding the right-most button until several LEDs blink once.
4. Release the right-most button



C:\Masters\1538\Lab1\MPFSImg2.bin

10

Open a web browser and **access** the webpage upload function by entering
http://UNIQUE-NAME/mpfsupload into the address bar. Use the host name defined in **Step 4**.
Upload the **MPFSImg2.bin** bundle of web pages to the target system when prompted.
Click the link for **Site Main Page**. Navigate the demo website specifically in the upper right corner where you should be able to confirm the switch, potentiometer and LED operations.



Helpful Suggestions for unfound *hostname*

In some PC configurations, Firewall settings can block browsers from properly connected via the *hostname* specification used in Step 12 and follow-on labs. If this is experienced, it is recommended to disable the PC firewall software for completion of the lab exercises.

Also, multiple unsuccessful attempts to access the development boards by *hostname* can cause an unusable browser cache configuration. It is helpful to try one of the following two procedures prior to repeating the rebuild/reprogram sequence:

- Execute *nbtstat -R* in a DOS CMD window to purge the browser cache OR - Use the new IP
- address that was assigned by the router in-lieu of the *hostname* in steps above

Sample Web Page Display



Additional Features shown in this web page

This sample web page demonstrates many of the capabilities of the Microchip TCP/IP Stack. If you finish early, you can try out the various features. The LEDs on the board can be controlled via the status box at the upper right. (If you've selected the Explorer 16, the left-most LED shares a pin with a pushbutton, and so it will not display correctly and be uncontrollable.) The board reports back the status of its pushbuttons and potentiometer after they are changed on the target system.



Results

You have just set up the TCPIP Demo App project on your development board and uploaded a sample set of web pages. When complete, you should see a page similar to the screen shown on the previous page: SAMPLE WEB PAGE DISPLAY.



Code Analysis

The TCP/IP Config Wizard utility was used to modify network software configuration settings via compiler macros (`#define`) stored in `TCPIPConfig.h`. This **utility** changes the header file in your project via designer input but also can be viewed and edited via a text editor. Open `TCPIPConfig.h` and find where the tool stored the updated host name and MAC address. You'll see many other settings as well, most of which can be configured by enabling advanced settings in the utility. Specific board configurations, as discussed earlier, are handled similarly in the `HardwareProfile.h` file.



TCPIPConfig.h

```

141 // =====
142
143 /* Default Network Configuration
144 *   These settings are only used if data is not found in EEPROM.
145 *   To clear EEPROM, hold BUTTON0, reset the board, and continue
146 *   holding until the LEDs flash. Release, and reset again.
147 */
148 #define MY_DEFAULT_HOST_NAME           "MCHPBOARD"
149
150 #define MY_DEFAULT_MAC_BYTE1           (0x00)
151 #define MY_DEFAULT_MAC_BYTE2           (0x04)
152 #define MY_DEFAULT_MAC_BYTE3           (0xA3)
153 #define MY_DEFAULT_MAC_BYTE4           (0x00)
154 #define MY_DEFAULT_MAC_BYTE5           (0x4C)
155 #define MY_DEFAULT_MAC_BYTE6           (0xA9)
156
157 #define MY_DEFAULT_IP_ADDR_BYTE1       (169ul)
158 #define MY_DEFAULT_IP_ADDR_BYTE2       (254ul)
159 #define MY_DEFAULT_IP_ADDR_BYTE3       (1ul)
160 #define MY_DEFAULT_IP_ADDR_BYTE4       (1ul)
161
162 #define MY_DEFAULT_MASK_BYTE1           (255ul)
163 #define MY_DEFAULT_MASK_BYTE2           (255ul)

```



Conclusions

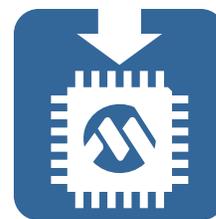
This lab has confirmed that your network setup and development board are operational. You have assigned a unique MAC address to your board, as well as a host name that can be accessed independently of the board's IP address. This host name operates through the NetBIOS Name Service, which is limited to the local subnet (in this case, your and your next door neighbor). Host name access outside of subnets is accomplished through DNS, which will be discussed later.

The IP address shown on the LCD screen has been automatically assigned by a DHCP server in a local router. DHCP is standard for most networks, and has replaced the need to hard code a static IP address. Static IP addresses can be configured when necessary.

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Lab Exercise 2

Using Wireshark for Protocol Debugging



Purpose

To obtain a working knowledge of using the Wireshark protocol sniffing software using the HTTP Get Message implementation from Lab 1 of this class.

Requirements

Software: Wireshark utility from 1538 Lab Build Installer v1.536
Environment: MPLAB[®] IDE 8.60 , X or later, 1538 Masters Install Script 1.536
C Compiler: MPLAB C18 v3..38 or later, C30 v3.30 or later, or C32 v1.12 or later
H/W Tools: PIC18F: PICDEM.net[™] 2, OR
PIC24FFJ128GA010 PIM: Explorer 16 w/ 10 Mbps, 10/100 Mbps PICtail Plus or MRF24WB0 OR
PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10 Mbps, 10/100 Mbps PICtail Plus or MRF24WB0
AND MPLAB REAL ICE[™] In-Circuit Emulator, or MPLAB ICD 3
AND DHCP Enabled Router (wired or wireless)
Lab Files: C:\Masters\1538\Lab2...

Objectives

- Utilize Wireshark to test and debug communication traffic between Host and Client.
- Understand some TCP/IP parameters such as: BOOTP, Payload content analysis, et. al.



Web Page Directory: C:\Master\1538\Lab2*

Procedures

1 Confirm Lab 1 was complete, including executing the [Replicate TCPIPCONFIG-HeaderFile.bat](#) confirming your unique hardware. If you have a previous MPLAB IDE project open, you must first close it by selecting from the menu: **File ▶ Close Workspace**

2 **Bundle and upload** the completed page to the development board with MPFS utility. The **MPFS2 Utility** generates the file `HTTPPrint.h`. This must be completed prior to compiling your MPLAB IDE project to include the dynamic variable callback functions already included in `customHTTPApp.c`.

Start ▶ Programs ▶ Microchip ▶ 1538 ▶ MPFS2

Confirm your `1538\Lab2\WebPages 2` folder and unique hostname is listed as the Device Address within the Upload Settings section. Click **Generate and Upload** to program your new pages to the development board. Confirm the utility successful completed.

3 **MPLAB File ▶ Open Project** 

Lab2-C18-PICDN2-ETH97.X for the PICDEM.net 2 with internal MAC/PHY setup

Lab2-C18-PICDN2-MRF24WB.X for the PICDEM.net 2 with Wireless MAC/PHY setup

Lab2-C30-EXP16-ENC28.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10Mbps module

Lab2-C30-EXP16-ENC624.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10/100Mbps module

Lab2-C30-EXP16-MRF24WB.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with WIFI module

Lab2-C32-EXP16-ENC28.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10Mbps module

Lab2-C32-EXP16-ENC624.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10/100Mbps module

Lab2-C32-EXP16-MRF24WB.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with WIFI module

4  **SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS.** Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER

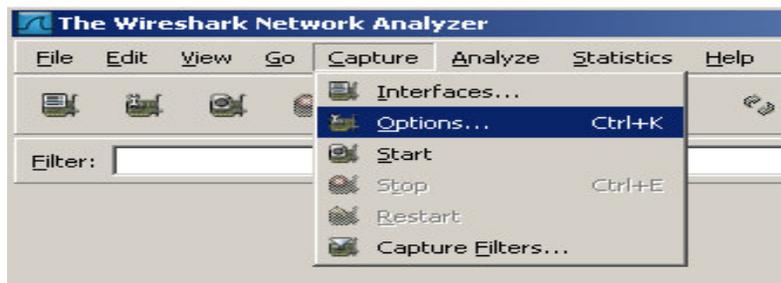


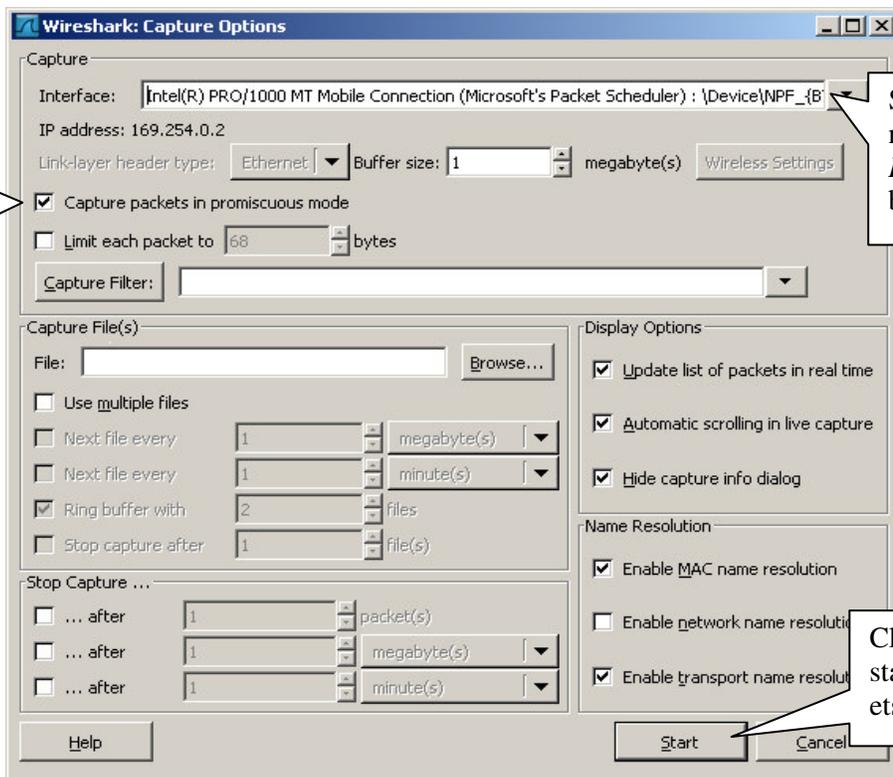
BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

5 **Open** Wireshark. Newer versions have a start up screen, and offer quick Network card selection and start of capture. Otherwise use the following to select the card and start a capture, as indicated in the next two screen shots:

1) **Select** CAPTURE/OPTIONS

2) Then **select** your PC's Ethernet card, Promiscuous mode, and Start a capture





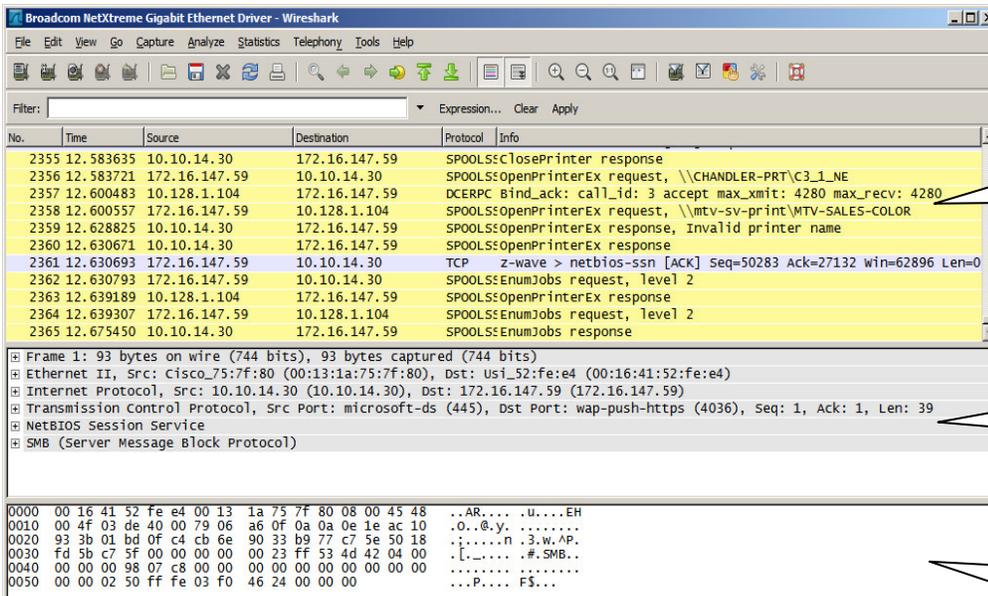
Ensure that *Capture packets in promiscuous mode* is checked.

Select your PC's network card in the *Interface* drop down box.

Click *Start* button to start capturing packets...

6

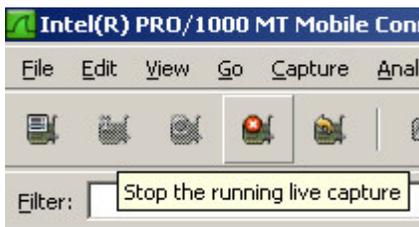
STOP the capture after you see packets being captured in Wireshark. The figure below shows Wireshark with its three main panes: Packet List, Packet Details, and Packet Bytes. The Stop icon is shown below.



"Packet List" Pane

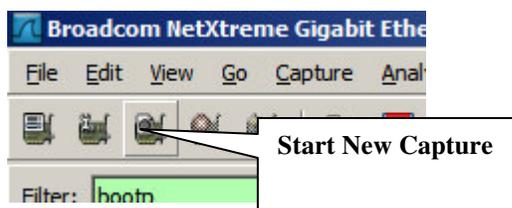
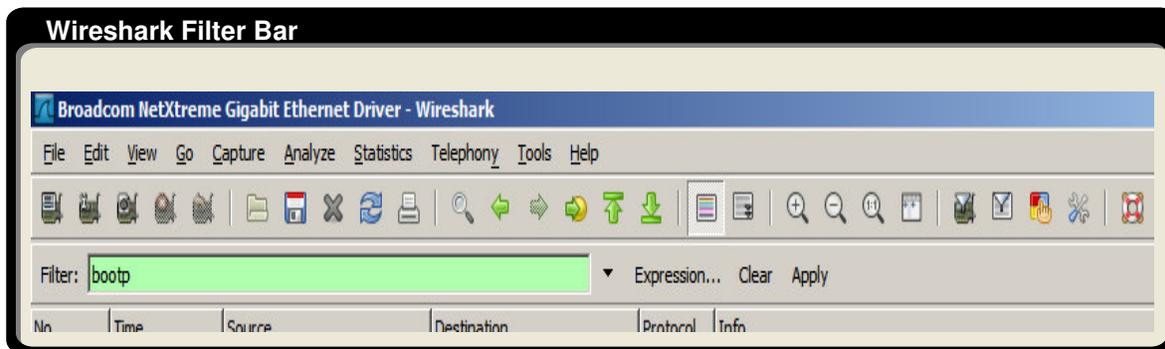
"Packet Details" Pane

"Packet Bytes" Pane



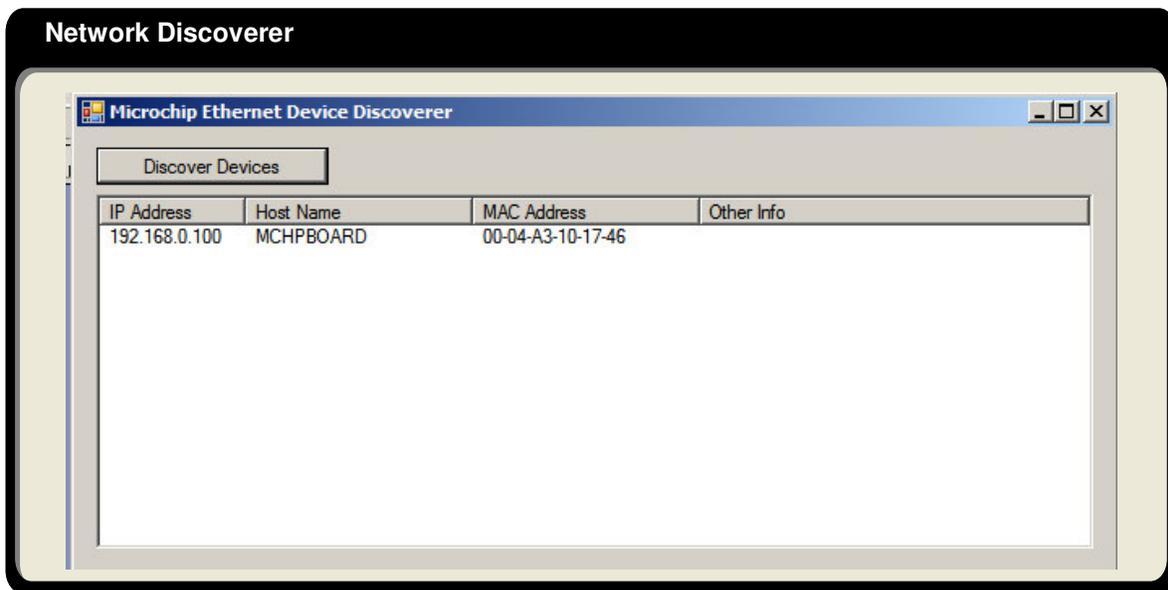
7

Enter a filter to look for DHCP protocols. Either use the expression builder or type directly into the filter bar. Bootp is a protocol keyword for DHCP. RESTART the capture again via the Start ICON shown below, disregard the request for saving. PRESS the Master Reset button on the board. STOP the capture and investigate the bootp packets.



8

Use the Ethernet Discoverer executable from Microchip tools to confirm your dev tool's IP address. **Start ▶ Programs ▶ Programs ▶ Microchip ▶ 1538 ▶ Microchip Ethernet Discoverer**



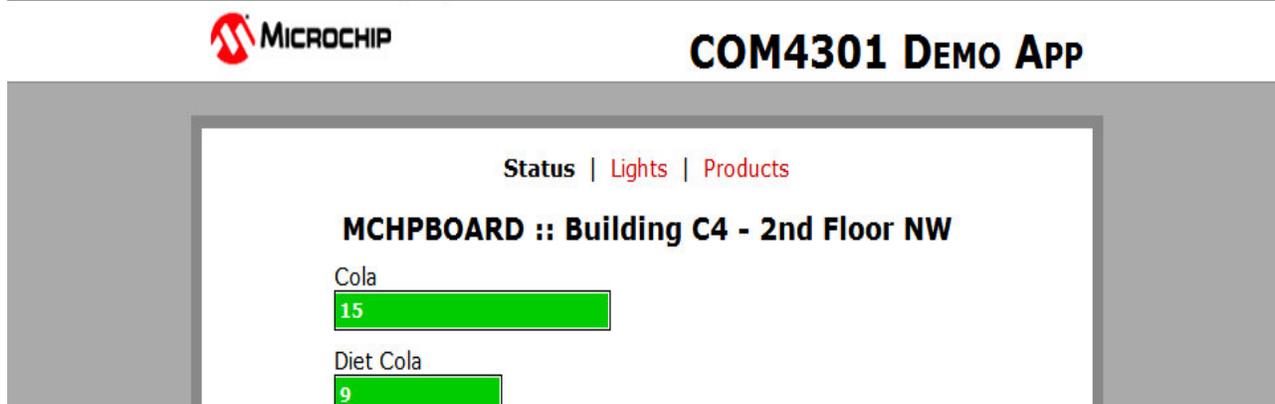
9

Change the filter again to only show your board's IP address. Type it into the filter bar or use the Expression Builder.

- To filter for all traffic with an IP address or destination source and destination use the following filter, ip.addr == <IP Address> with your board's IP address
- If you find too many results, filter on HTTP as well : Example: ip.addr == <IP Address> && http

Notice the capture window is reduced to frames only associated with that IP address.

- 10** **RESTART** the capture. Open a web browser and point to **http://UNIQUE-NAME/** specified in Lab 1. Stay on the STATUS page which is default when receiving the index.htm page. **STOP** the Wireshark capture sequence. Observe the frames monitored by Wireshark. Note the TCP socket connection frames.

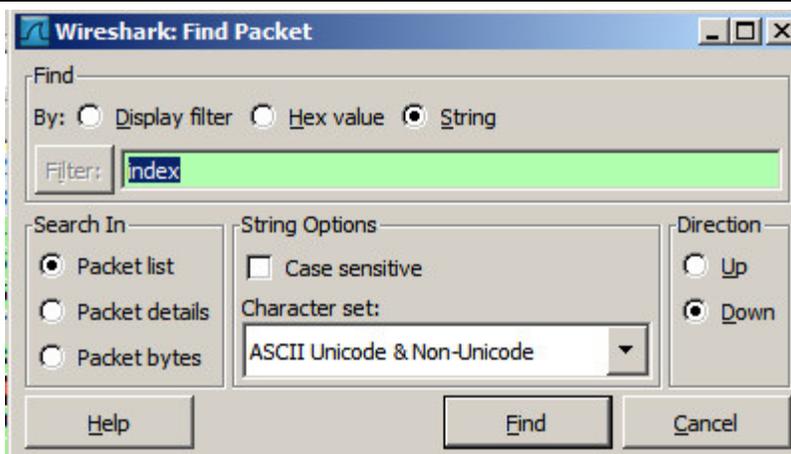


- 11** View the capture in Wireshark utility to follow a TCP Stream for Payload and Socket processing. Use the 'Find Packet...' command to display only the packets associated with the TCP transaction for the index.htm page loading. Select this from the menu > Edit > Find Packet, or Ctrl-F. Notice the packet where the first instance of the string is found is highlighted, shown on the screen at the top of the next page.

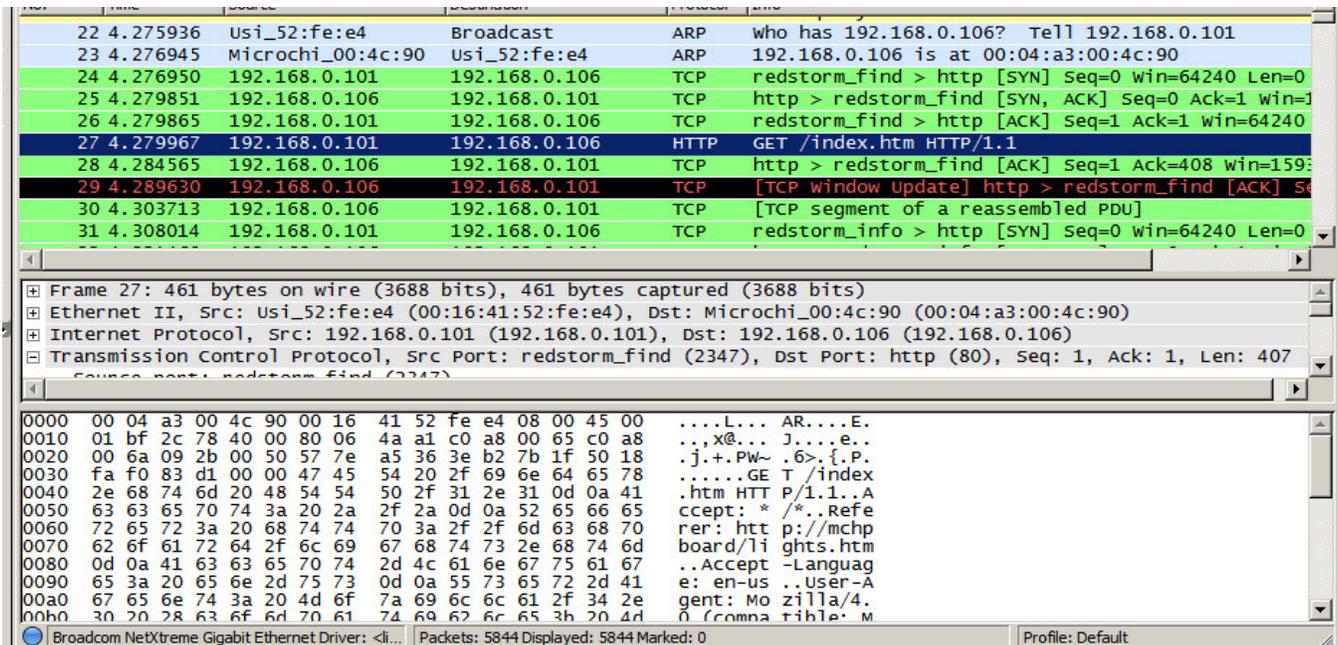


Helpful Suggestions for Wireshark Packet Finding

When a browser sends a request for a file from an HTTP server, it sends out the request in ASCII text. Therefore, the Find dialog box should use the 'String' search filter. Also, start with the packet finder searching in the PACKET LIST, as shown in the display below.



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12

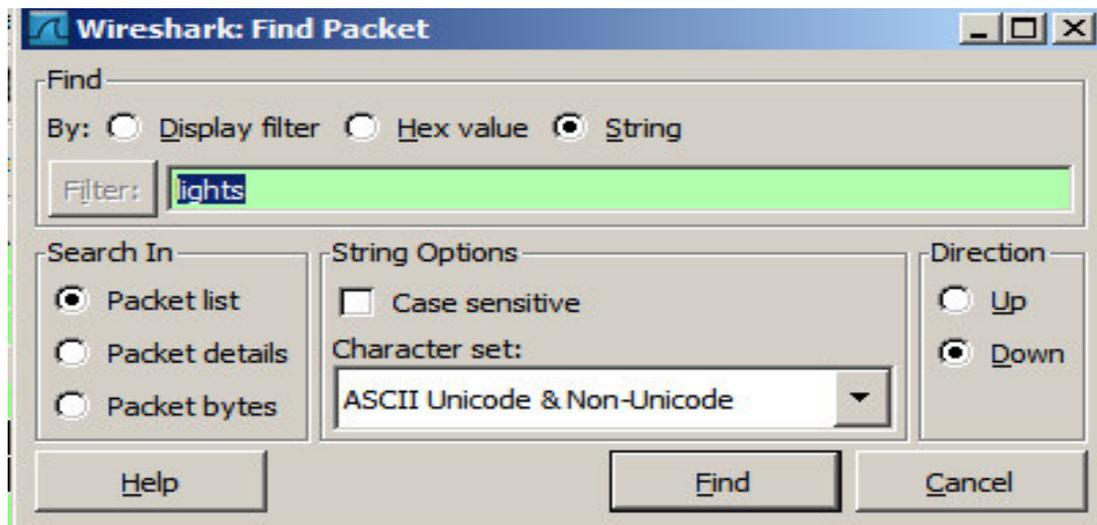
RESTART the capture.

Select the lights webpage heading in the browser at the top of the screen.

STOP the Wireshark capture sequence. Observe the frames monitored by Wireshark.

13

Now use the 'Find Packet...' command to display only the packets associated with the TCP transaction for the lights.htm page loading. Select this from the menu > Edit > Find Packet, or Ctrl-F.



Results

The Wireshark utility has been used to monitor the communication from a PC browser to the MCU acting as a webpage server. Specific IP addresses were filtered for, and a TCP communication stream was observed.

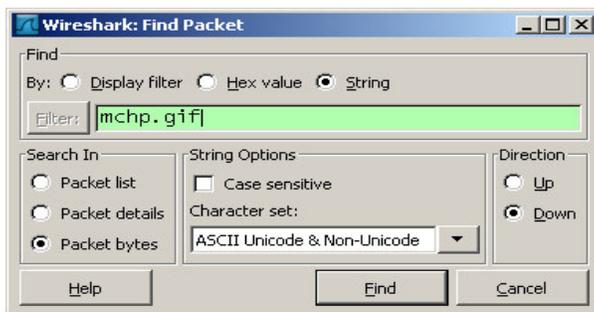
Analysis

Wireshark can be used to investigate the communication traffic by inserting a PC into the network. The utility can be used to see all traffic, or can be configured to filter traffic for a defined subset of the communication partners. Filters can also be used to track specific protocols and therefore help the designer confirm their firmware is behaving as expected.

15 Bonus Procedure

Figure out how to display only the packets associated with the TCP associated with downloading the mchp.gif file inside this design. Use the 'Find' command by selecting:

> [Edit > Find Packets...](#)



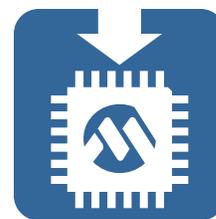
- 16 After finding the packet, **ALTER** THE TIME COLUMN PARAMETERS to suit your need for the timing calculation. Then **USE** FOLLOW THE TCP STREAM FEATURE. Application transmit performance can be calculated by: (mchp.gif file size)/(time elapsed for entire TCP transaction).

! Wireshark Menu Altering

The *Time* column in Wireshark can be configured to display several different values (time since beginning of capture, time since last packet, etc.). Remember that right clicking on a packet in the packet pane will bring up a useful menu.

Lab Exercise 3

Integrating an Application with the Stack



Purpose

For many designs, you will be integrating an existing application with the stack. For new designs, it is still important to understand the fundamental design of the stack and where to place your application's code.

In this lab, you will take the example vending machine application demonstrated earlier and integrate it with the stack. Due to the complexity of the stack, it is generally easier to integrate your application into the stack rather than the other way around. This lab will walk you through those steps, and upon completion the vending machine and the stack will be operating separately within the device. The following labs will focus on them working cooperatively.

Requirements

Software: Completed Lab 1 to support network settings
Environment: MPLAB® IDE 8.60, X, or later, 1538 Masters Installer 1.536
C Compiler: MPLAB C18 v3.38 or later, C30 v3.30 or later, or C32 v1.12 or later
H/W Tools: PIC18F: PICDEM.net™ 2, or
 PIC24FFJ128GA010 PIM: Explorer 16 w/ 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0 or
 PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0
 AND MPLAB Real ICE™, or MPLAB ICD 3
 AND DHCP Enabled Router (wired or wireless)
Lab Files: C:\Masters\1538\Lab3...

Objectives

- Experience the procedural steps for combing an existing firmware application with the TCP/IP stack
- Practice identifying the desirable locations for the firmware application within the TCPIP stack.



C:\Masters\1538\Lab3*



C:\Masters\1538\Vending Machine\VendingMachine.*



The Vending Machine application is implemented in the Vending Machine Project Directory above. The core of the application is implemented in two source files.

Procedures

1

MPLAB File ▶ **Open Project****Lab3-C18-PICDN2-ETH97** for the PICDEM.net 2 with internal MAC/PHY setup**Lab3-C18-PICDN2-MRF24WB** for the PICDEM.net 2 with Wireless MAC/PHY setup**Lab3-C30-EXP16-ENC28** for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10Mbps module**Lab3-C30-EXP16-ENC624** for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10/100Mbps module**Lab3-C30-EXP16-MRF24WB** for the Explorer 16 with PIC24F/dsPIC33F PIMs with WIFI module**Lab3-C32-EXP16-ENC28** for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10Mbps module**Lab3-C32-EXP16-ENC624** for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10/100Mbps module**Lab3-C32-EXP16-MRF24WB** for the Explorer 16 with PIC32MX3xx/4xx PIMs with WIFI module

2

Copy files `VendingMachine.c` and `VendingMachine.h` from the `Vending Machine` directory to the Lab 3 project directory. Use **Windows Explorer** or **My Computer**.

3

Add the two files you copied to your MPLAB project. You may need to select “All Source And Header Files” from the dropdown list for “Files of type” in order to see both the `.c` and `.h` file. **Project** ▶ **Add Files** ▶ `VendingMachine.c` and `VendingMachine.h`.

4

Open `VendingMachine.h` and Comment out the section “Required Headers”. Also Insert `#include` “TCPIP Stack/TCPIP.h” just below as shown. These headers and insertion integrate this file with TCPIP stack files. Save the changes you make. **File** ▶ **Save****VendingMachine.h**

```

53
54
55 /*****
56 Section:
57 Required Headers
58 *****/
59 // #include "Compiler.h"
60 // #include "GenericTypeDefs.h"
61 // #include "HardwareProfile.h"
62 // #include "Delay.h"
63 // #include "LCDBlocking.h"
64 #include "TCPIP Stack/TCPIP.h"
65
66

```

4

5

Open `MainDemo.c` and Insert `#include VendingMachine.h` in so as to gain access to the vending machine application data. Place this directly below the directive for `MainDemo.h` line.**MainDemo.c**

```

69 #include "TCPIP Stack/ZeroconfMulticastDNS.h"
70 #endif
71
72 // Include functions specific to this stack application
73 #include "MainDemo.h"
74 #include "VendingMachine.h"
75
76 // Used for Wi-Fi assertions
77 #define WF_MODULE_NUMBER WF_MODULE_MAIN_DEMO
78
79 // Declare AppConfig structure and some other supporting stack variables
80 APP_CONFIG AppConfig

```

5

6

Insert a call to the vending machine's initialization function `InitializeVend()` in `main()`. This should be placed immediately following the call to `InitAppConfig()` on line 262.



MainDemo.c

```

194 // required by the UART configuration routines
195 TickInit();
196 #if defined(STACK_USE_MPF2)
197 MPFSInit();
198 #endif
199
200 // Initialize Stack and application related NV variables into AppConfig.
201 InitAppConfig();
202 InitializeVend();
203
204 // Initiates board setup process if button is depressed
205 // on startup
206 if(BUTTON0_IO == 0u)
207 {
208     #if defined(EEPROM_CS TRIS) || defined(SPIFLASH_CS TRIS)

```

6

7

Replace the contents of `ProcessIO()` from line 644. Instead of performing an A/D conversion, call `VendingMachine()` to perform any necessary vending machine tasks.



MainDemo.c

```

586 LCDText[LCDPos] = 0;
587 LCDUpdate();
588 #endif
589 }
590
591 // Processes A/D data from the potentiometer
592 static void ProcessIO(void)
593 {
594     VendingMachine();
595 }
596
597
598
599 Function:
600 static void InitializeBoard(void)
601

```

7



The Application Global Variables within `Vending Machine.c` declare the storage locations and define the state machine used by for the vending machine application. The LCD Functions section writes the various menus to the LCD display. Finally, the Initialization section configures the product names, prices, and stocks when the device boots.



VendingMachine.c-Global Variables

```

59 Section:
60 Vending Machine Application Global Variables
61 *****
62
63 VEND_ITEM Products[MAX_PRODUCTS]; // All items in the machine
64 BYTE machineDesc[33]; // Machine description string
65 BYTE curItem; // Current product being display
66 BYTE curCredit; // Current deposit credit, as nu
67
68 static enum
69 {
70     SM_IDLE = 0u, // No events are pending
71     SM_DEBOUNCE_DOWN, // Button press detected...verify the ev
72     SM_ADD_COIN // "Insert" coin "dispensed"

```



VendingMachine.c: LCD writes

```

237 // Display the boot message on the LCD
238 strcpypgm2ram((char*)LCDText, "Microchip      Vending Machine");
239 LCDUpdate();
240 }
241
242
243 /*****
244 Section:
245 Vending Machine LCD Functions
246 *****/
247 static void WriteLCDMenu(void)
248 { // Update the LCD screen
249
250     // Blank the LCD display
251     LCDErase();
252
253     // Show the name
254     strcpy((char*)LCDText, (char*)Products[curItem].name);
255     LCDText[strlen((char*)Products[curItem].name)] = ' ';
256
257     // Show the price, or sold out status
258     if(Products[curItem].stock == 0)
259         memcpypgm2ram(&LCDText[12], (ROM void*)"SOLD", 4);
260     else

```



VendingMachine.c: Initialization

```

204 Section:
205 Vending Machine Initialization
206 *****/
207 void InitializeVend(void)
208 {
209     // Vending machine specific defaults
210     strcpypgm2ram((char*)Products[0].name, (ROM char*)"Cola");
211     strcpypgm2ram((char*)Products[1].name, (ROM char*)"Diet Cola");
212     strcpypgm2ram((char*)Products[2].name, (ROM char*)"Root Beer");
213     strcpypgm2ram((char*)Products[3].name, (ROM char*)"Orange");
214     strcpypgm2ram((char*)Products[4].name, (ROM char*)"Lemonade");
215     strcpypgm2ram((char*)Products[5].name, (ROM char*)"Iced Tea");
216     strcpypgm2ram((char*)Products[6].name, (ROM char*)"Water");
217     Products[0].price = 4;
218     Products[1].price = 4;
219     Products[2].price = 4;
220     Products[3].price = 4;
221     Products[4].price = 5;
222     Products[5].price = 7;
223     Products[6].price = 8;
224     Products[0].stock = 15;
225     Products[1].stock = 9;
226     Products[2].stock = 22;
227     Products[3].stock = 18;
228     Products[4].stock = 4;
229     Products[5].stock = 29;
230     Products[6].stock = 14;
231
232     strcpypgm2ram((char*)machineDesc, (ROM char*)"Building C4 - 2nd Floor NW");
233     machineDesc[32] = '\0';
234     curItem = 0;
235     curCredit = 0;
236
237     // Display the boot message on the LCD
238     strcpypgm2ram((char*)LCDText, "Microchip      Vending Machine");
239     LCDUpdate();
240 }

```

8



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

9

Verify that the vending machine operates as discussed in the initial demo. Unexpected output on the LCD display will be corrected in the next step.

Verify that the web pages accessed during Lab 2 are still available.

10

In some versions of the stack, annoying messages are received on line 2 of the LCD display. If that occurs; Comment out the call to `PingDemo()` in the main program loop to disable this output.

The “Ping timed out” message is generated by the ping demo when the right-most button is pressed.

Comment out the call to `DisplayIPValue()` as it writes the IP address to the LCD.

These deletions will **eliminate** the output of extraneous data to the LCD.



MainDemo.c

10

```

414     //PingDemo();
415     #endif
416
417     #if defined(STACK_USE_SNMP_SERVER) && !defined(SNMP_TRAP_DISABLED)
418     //User should use one of the following SNMP demo
419     // This routine demonstrates V1 or V2 trap formats with one variable binding.
420     SNMPTrapDemo();
421     #if defined(SNMP_STACK_USE_V2_TRAP)
422     //This routine provides V2 format notifications with multiple (3) variable bindings
423     //User should modify this routine to send v2 trap format notifications with the required varbinds.
424     //SNMPV2TrapDemo();
425     #endif
426     if(gSendTrapFlag)
427         SNMPSendTrap();
428     #endif
429
430     #if defined(STACK_USE_BERKELEY_API)
431     BerkeleyTCPClientDemo();
432     BerkeleyTCPServerDemo();
433     BerkeleyUDPClientDemo();
434     #endif
435
436     ProcessIO();
437
438     // If the local IP address has changed (ex: due to DHCP lease change)
439     // write the new IP address to the LCD display, UART, and Announce
440     // service
441     if(dwLastIP != AppConfig.MyIPAddr.Val)
442     {
443         dwLastIP = AppConfig.MyIPAddr.Val;
444
445         #if defined(STACK_USE_UART)
446             putsUART((ROM char*)"r\nNew IP Address: ");
447         #endif
448
449         //DisplayIPValue(AppConfig.MyIPAddr);
450
451         #if defined(STACK_USE_UART)

```

10

11



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

12

Confirm the Router assigns a new IP Address.

Verify that the undesired messages no longer appear on the LCD screen.



Results

Your project now has a vending machine operating simultaneously with the TCP/IP Stack. While the two functions do not interact with each other yet, the basic functionality is working



Code Analysis

The vending machine application was implemented as a state machine, which is common for many simple microcontroller-based systems. Since each state executes for only a brief period, it was relatively easy to integrate into the stack. However, the general model and code placement applies for more complex applications as well. In general, initialization code should be called after the `InitAppConfig()` call. This code will be executed once when your device boots. Application code should be placed either at the end of the main stack loop or in the `ProcessIO()` function.

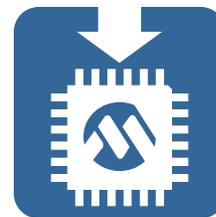


Conclusions

Although no new functionality has been gained, the vending machine is now much closer to being network-enabled. Integration with the stack is the most challenging task because it requires (in many cases) a new way of thinking about the application. A few integration issues still remain, which will be explored in the next lab.

Lab Exercise 4

Remove Blocking Code



Purpose

Networked applications must handle a significant amount of background processing in order to keep the network connection alive. To accomplish these time-sensitive events, the Microchip TCP/IP Stack operates in a co-operative multi-tasking fashion. This eliminates the need for an RTOS, as well as the need for interrupts and overhead.

However, it means that your application must be implemented without any code that may block the processor. In this lab, you will witness how a blocking loop can affect the TCP/IP Stack, and will learn how to take steps to avoid such loops in your application.

Requirements

Environment: MPLAB® IDE 8.60, X, or later, 1538 Masters Installer 1.536
C Compiler: MPLAB C18 v3.38 or later, C30 v3.30 or later, or C32 v1.12 or later
H/W Tools: PIC18F: PICDEM.net™ 2, or
 PIC24FFJ128GA010 PIM: Explorer 16 w/ 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0 or
 PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0
 AND MPLAB Real ICE™, or MPLAB ICD 3
 AND DHCP Enabled Router (wired or wireless)
Lab Files: C:\Masters\1538\Lab4..

Objectives

- Identify non-conforming application code that can disrupt the required operational flow of the TCP/IP stack
- Practice making application code modifications to ensure compatible coexistence of two code sets

Procedures

- 0 **Confirm** the operation of the blinking LED per the description below:
 With your application from Lab 3 running, notice the blinking status LED on your development board. What happens to that light when a message change is displayed on the LCD? (The effect is most visible when you attempt to insert more than \$5.00 of credit into the machine.) Stable blinking operation of this LED signifies that the TCP/IP Stack is being called frequently. When the status light is not blinking, the stack is not running and cannot respond to incoming network traffic. The existing vending machine code uses a blocking loop to time the display message. This needs to be corrected.



C:\Masters\1538\Lab4*

1

MPLAB File ▶ **Open Project****Lab4-C18-PICDN2-ETH97.X** for the PICDEM.net 2 with internal MAC/PHY setup**Lab4-C18-PICDN2-MRF24WB.X** for the PICDEM.net 2 with Wireless MAC/PHY setup**Lab4-C30-EXP16-ENC28.X** for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10Mbps module**Lab4-C30-EXP16-ENC624.X** for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10/100Mbps module**Lab4-C30-EXP16-MRF24WB.X** for the Explorer 16 with PIC24F/dsPIC33F PIMs with WIFI module**Lab4-C32-EXP16-ENC28.X** for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10Mbps module**Lab4-C32-EXP16-ENC624.X** for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10/100Mbps module**Lab4-C32-EXP16-MRF24WB.X** for the Explorer 16 with PIC32MX3xx/4xx PIMs with WIFI module

2

Open the vending machine source file `VendingMachine.c`. Locate the blocking FOR loop in the `SM_DISPLAY_WAIT` state inside of `VendingMachine()`. This loop consumes processing cycles by performing a meaningless task. Mark this loop as commented out as shown in the example below.

**About Timing Loops**

A common method for implementing delays is to cause the processor to complete some meaningless task, such as counting to 10,000, or to call one of the `Delay()` functions that does this internally. However, code constructs such as these block the processor and waste MCU resources that could otherwise be spent handling incoming Ethernet packets or other network functions. Loops of this type should be avoided.

Instead, use the provided `Tick` module. The `Tick` module is interrupt-driven, and is based on the hardware clock. It is stable and accurate, and can be used to implement non-blocking delays by comparing current times to timeouts. Since it is hardware-based, it is also suitable for use as a Real Time Clock.

3

Insert a comparison of `TICK` values to determine if enough time has elapsed. If the timeout has occurred, advance the state machine. Otherwise, just `break` and return to the main stack application. The stack will call the vending machine to perform the comparison again later. Use the example shown below.

**VendingMachine.c**

```

169         break;
170
171         case SM_DISPLAY_WAIT:
172             // Wait for the timeout to occur before continuing
173             //for(displayTimeout *= 1000; displayTimeout > 0; displayT
174             // DelayMs(1);
175             if((LONG)(TickGet() - displayTimeout) > (LONG)0)
176                 smVend = SM_SHOW_MENU;
177             break;
178
179         case SM_SHOW_MENU:

```

2

3

4

Change the declaration of this value at the top of `VendingMachine()` to its initialization to indicate two seconds rather than just the number 2. Use the macro `TICK_SECOND` to calculate this value. Your code should match the sample below.



VendingMachine.c

```

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.....
Section:
Vending Machine Implementation
.....
void VendingMachine(void)
{
    static DWORD displayTimeout = (2 * TICK_SECOND);
    // Vending Machine State Machine
    switch(smVend)
    {
        case SM_IDLE:
            // Wait for a button press
            if(BUTTON0_IO == 0 || BUTTON1_IO == 0 || BUTTON2_IO == 0 || BUTTON3_IO == 0)
                smVend = SM_DEBOUNCE_DOWN;
            DelayMs(1);

```

4

5

Change the two instances where `displayTimeout` is set.

Use a relative time

based on `TickGet()` and `TICK_SECOND` as indicated below. The variable `displayTimeout` is now allocated as a `TICK` and configured to expire on a relative timeout value. The last step in this conversion is to replace the code that assigns absolute delays to `displayTimeout` with an assignment relative to the current `TICK` value.



VendingMachine.c

```

127
128
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145
146
147
148
149
150
151
152
153
154
155
    strcpypgm2ram((char*)LCDText, (ROM char*)" Coin F
    LCDUpdate();
    displayTimeout = TickGet() + 4 * TICK_SECOND;
    smVend = SM_DISPLAY_WAIT;
}
break;

case SM_TRY_VEND:
    // Try to vend a product
    if(Products[curItem].stock == 0)
    { // Product is sold out
        strcpypgm2ram((char*)LCDText, (ROM char*)" SOI
    }
    else if(Products[curItem].price > curCredit)
    {
        strcpypgm2ram((char*)LCDText, (ROM char*)"Price:
        WritePriceLCD(Products[curItem].price, 8);
        WritePriceLCD(curCredit, 24);
    }
    else
    {
        strcpypgm2ram((char*)LCDText, (ROM char*)" vend
        curCredit -= Products[curItem].price;
        Products[curItem].stock--;
    }
    LCDUpdate();
    displayTimeout = TickGet() + 2 * TICK_SECOND;
    smVend = SM_DISPLAY_WAIT;
    break;

```

5

5

6



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

7

Verify that the vending machine still functions.

1. Ensure that your web pages from Lab 2 are still accessible via a browser.
2. Verify that the status LED continues to blink, even when a status message is displayed on the screen.
 - i. Test when vending is attempted with insufficient credit.
 - ii. Test when a coin is returned for depositing over \$5.00.
 - iii. Test when a product is vended.
 - iv. Test when a product is sold out.



To use the tick module, replace the blocking call by checking the current time using TickGet. Then add an additional state to wait for the timeout. Transition to this state and return to the main loop. When the loop returns to your application, compare the stored value with the current time. You can use simple subtraction, since Ticks are stored as signed integers and will automatically overflow. The TICK_SECOND macro is based on the instruction frequency, and can be used for comparisons against elapsed time. You can also multiply or divide this value to obtain various resolutions. Tick is an unsigned value. Type-casting to LONG forces the result to be a signed value, which will automatically take care of overflow. Assume a TICK is only one byte. Say TickGet is equal to 253, and TICK_SECOND/10 is actually 10. That means that “doneAt” will be set to 7 after overflow. When TickGet returns 255, you’ll have $255 - 7$. That’s 248, or 1111 1000b. Cast that to a LONG and the first becomes a sign bit. That binary value equates to -8, and so $-8 < 0$ and your timeout has not yet happened. When TickGet rolls over and returns 3, you’ll have $3 - 7$. You’ll get -4 after the cast, and your timeout will fail. Once TickGet has incremented 10 times you’ll be at 8. You’ll have $8 - 7$, which will be greater than zero and your timeout will succeed. This works in many other cases, but you may have to pull out some old binary arithmetic rules to prove it to yourself.



Results

When the lab is completed correctly, the status LED will continue to blink without interruption while messages are being displayed on the LCD. This signifies that application is not blocking the processor and that the stack can complete its tasks in a timely fashion.



Code Analysis

The examples provided in this lab implement a timer without blocking loops. A single state is used for the timeout stage, and the various machine states can set when a timeout will occur. Timeouts are stored in `displayTimeout`, which is declared as a `TICK` value. The timeout value is calculated as the current time (obtained via `TickGet()`), plus some multiple of `TICK_SECOND`. This method is suitable for measuring time differences from a few microseconds to a few hours. (It's companion methods `TickGetDiv256()` and `TickGetDiv64K()` are valid for a few weeks or several years, respectively.) The value of `TICK_SECOND` is calculated from the value of `GetInstructionClock()` as specified in `HardwareProfile.h`. `TICK` values are stored as 32-bit unsigned integers. When a time increment is added (such as `2*TICK_SECOND`), this could result in overflow. Similarly underflow may result when the subtraction is performed. The subtraction of `TICK` values, when cast to a `LONG`, compensates for this by reestablishing the sign bit. This allows for valid comparisons in all cases.



Bonus Procedure

8

Several calls to `DelayMs()` remain in the code to help de-bounce the pushbuttons. Since the stack loop now executes between each state, see if any of these can be removed without affecting operation. This will be dependent on your platform, as the faster processors may still loop too quickly to avoid the transient periods.



Conclusion

The vending machine is now completely integrated, and neither task will interfere with the other. With this complete, you are now ready to be adding network features to the device.

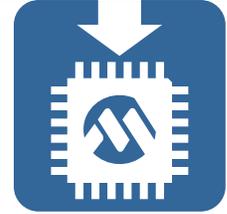
The principles learned in these past two labs apply to all stack applications:

1. Break long tasks into states, allowing the stack to execute frequently.
2. Use the Tick module instead of blocking loops for timed events.

The co-operative multi-tasking methodology of the stack is flexible, and will consume as little or as much processor time as the application supplies. If necessary, stack operation can be interrupted by the application for a few hundred milliseconds up to even a few seconds. While this is not desirable (and should not be a frequent occurrence), most network application protocols will not time out until several seconds have elapsed without communication. However, the application will risk overrunning its RX buffer and losing data during this time. As a general rule, applications should attempt to run the main stack loop at least every 10 or 20ms, with 1-2ms being the target for best performance.

Lab Exercise 5

Web-based Monitoring with Dynamic Variables



Purpose

The first network feature to be implemented for this vending machine is the ability to determine its stock remotely. Having already decided upon a web page for monitoring, the next step is to link the vending machine data into a web page. Example web pages have already been provided for this project. However, they are just static pages with no mechanism to populate vending machine data into the page. In this lab, you will program the first page to display the product name and remaining stock level as reported by the vending machine.

Requirements

Environment: MPLAB® IDE 8.60 , X, or later, MPFS Utility, 1538 Masters Installer 1.536
C Compiler: MPLAB C18 v3.38 or later, C30 v3.30 or later, or C32 v1.12 or later
H/W Tools: PIC18F: PICDEM.net™ 2, or
 PIC24FFJ128GA010 PIM: Explorer 16 w/ 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0 or
 PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0
 AND MPLAB Real ICE™ , MPLAB ICD3 or MPLAB ICD 2
 AND DHCP Enabled Router (wired or wireless)
Lab Files: C:\Masters\1538\Lab5....

Objectives

- Implement dynamic replacement of static variables within HTML files for web server applications
- Utilize Callback procedure methodology between the HTTP2 module and customer application firmware



Web Page Directory:
 C:\Masters\1538\Lab5\WebPages2

Procedures

- 1** Confirm design files in the `WebPages2` folder in **Lab 5** match the `Sample Web Pages` in C:\Masters\1538 folder.
- 2** Open `index.htm` from the `WebPages2` directory in **Crimson Editor**.
Start ▶ Programs ▶ Crimson Editor ▶ Crimson Editor



C:\Masters\1538\Lab5*

5

MPLAB File ▶ **Open Project**

Lab5-C18-PICDN2-ETH97.X for the PICDEM.net 2 with internal MAC/PHY setup
Lab5-C18-PICDN2-MRF24WB.X for the PICDEM.net 2 with Wireless MAC/PHY setup
Lab5-C30-EXP16-ENC28.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10Mbps module
Lab5-C30-EXP16-ENC624.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10/100Mbps module
Lab5-C30-EXP16-MRF24WB.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with WIFI module
Lab5-C32-EXP16-ENC28.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10Mbps module
Lab5-C32-EXP16-ENC624.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10/100Mbps module
Lab5-C32-EXP16-MRF24WB.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with WIFI module

Open `CustomHTTPApp.c` within MPLAB's project window.

6

Remove all the `HTTPPrint_*` functions within the "Dynamic Variable Callback Functions" section (These callbacks are for the demo application, most of which are no longer needed.) except for `HTTPPrint_version()` and `HTTPPrint_builddate()`.

**CustomHTTPApp.c (delete unused sections)**

Continue deleting thru the lines on the next page

6

```

1402 //*****
1403 //***** Lab5 Step6: Start the section delete here and continue to line 1907*****
1404 //*****
1405
1406
1407 ROM BYTE HTML_UP_ARROW[] = "up";
1408 ROM BYTE HTML_DOWN_ARROW[] = "dn";
1409
1410 void HTTPPrint_btn(WORD num)
1411 {
1412     // Determine which button
1413     switch(num)
1414     {
1415     case 0:
1416         num = BUTTON0_IO;
1417         break;
1418     case 1:
1419         num = BUTTON1_IO;
  
```



CustomHTTPApp.c (delete unused sections)

```

1890
1891 void HTTPPrint_status_ok(void)
1892 {
1893     if(lastSuccess)
1894         TCPPutROMString(sktHTTP, (ROM BYTE*)"block");
1895     else
1896         TCPPutROMString(sktHTTP, (ROM BYTE*)"none");
1897     lastSuccess = FALSE;
1898 }
1899
1900 void HTTPPrint_status_fail(void)
1901 {
1902     if(lastFailure)
1903         TCPPutROMString(sktHTTP, (ROM BYTE*)"block");
1904     else
1905         TCPPutROMString(sktHTTP, (ROM BYTE*)"none");
1906     lastFailure = FALSE;
1907 }
1908 //*****
1909 //***** Lab5 Step6: End the section delete here *****
1910 //*****
1911
1912 #endif
1913

```

6

7

Insert a callback function named `HTTPPrint_hostname()` to this section of the file. This function has no parameters and returns no value. Within the function, use `TCPPutString()` to print the hostname from its RAM location, `AppConfig.NetBIOSName`, to the TCP socket, `sktHTTP`. For more information about callbacks, refer to the info box labeled on the topic below..



CustomHTTPApp.c

```

1322 {
1323     curHTTP.callbackPos = 0x01;
1324     if(TCPIsPutReady(sktHTTP) < strlenpgm((ROM char*) __DATE__ " " __TIME__))
1325         return;
1326
1327     curHTTP.callbackPos = 0x00;
1328     TCPPutROMString(sktHTTP, (ROM void*) __DATE__ " " __TIME__);
1329 }
1330
1331 void HTTPPrint_version(void)
1332 {
1333     TCPPutROMString(sktHTTP, (ROM void*) VERSION);
1334 }
1335
1336 void HTTPPrint_hostname(void)
1337 {
1338     TCPPutString(sktHTTP, AppConfig.NetBIOSName);
1339 }
1340

```

7



About Callback Functions

Callback functions are a concept of event-driven programming. For the HTTP2 web server, an event occurs when a dynamic variable is encountered in your HTML code. The response, handled by your callback function, is to print text or data to the web browser.

You do not need to worry about how or when the callback is invoked. The HTTP2 server, along with the `HTTPPrint.h` file generated by the MPFS2 Utility, take care of this for you.

8

Add a second callback function named `HTTPPrint_machineDesc()` to this section of the file. This function also has no parameters and returns no value. Adding this function is slightly more involved.

9

StepA, Insert a `#include VendingMachine.h` entry at the top of the file right after the existing `#include Main-Demo.h` entry. This provides a reference to the `machineDesc` string.

StepB, Insert an `if` loop that uses `TCPIsPutReady()` to confirm buffer space. The `machineDesc` string may be up to 32 bytes long, which is longer than the 16 bytes the HTTP2 web server guarantees are available. So, the `HTTPPrint` call must follow the ensuring of at least 32 bytes are free in the TCP buffer. If the buffer is too small, set a non-zero flag in `curHTTP.callbackPos` and return, which will request to be called again when more space is available.

c

CustomHTTPApp.c

```

53  *****/
54  #define __CUSTOMHTTPAPP_C
55
56  #include "TCPIPConfig.h"
57
58  #if defined(STACK_USE_HTTP2_SERVER)
59
60  #include "TCPIP Stack/TCPIP.h"
61  #include "MainDemo.h" // Needed for SaveAppConfig() prototype
62  #include "VendingMachine.h"
63  /***/

```



```

1392
1393 void HTTPPrint_hostname(void)
1394 {
1395     TCPPutString(sktHTTP, AppConfig.NetBIOSName);
1396 }
1397
1398 void HTTPPrint_machineDesc(void)
1399 {
1400     if(TCPIsPutReady(sktHTTP) < 32)
1401     {
1402         curHTTP.callbackPos = 0x01;
1403         return;
1404     }
1405
1406     curHTTP.callbackPos = 0x00;
1407     TCPPutString(sktHTTP, machineDesc);
1408 }
1409

```

9

8

9

10



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



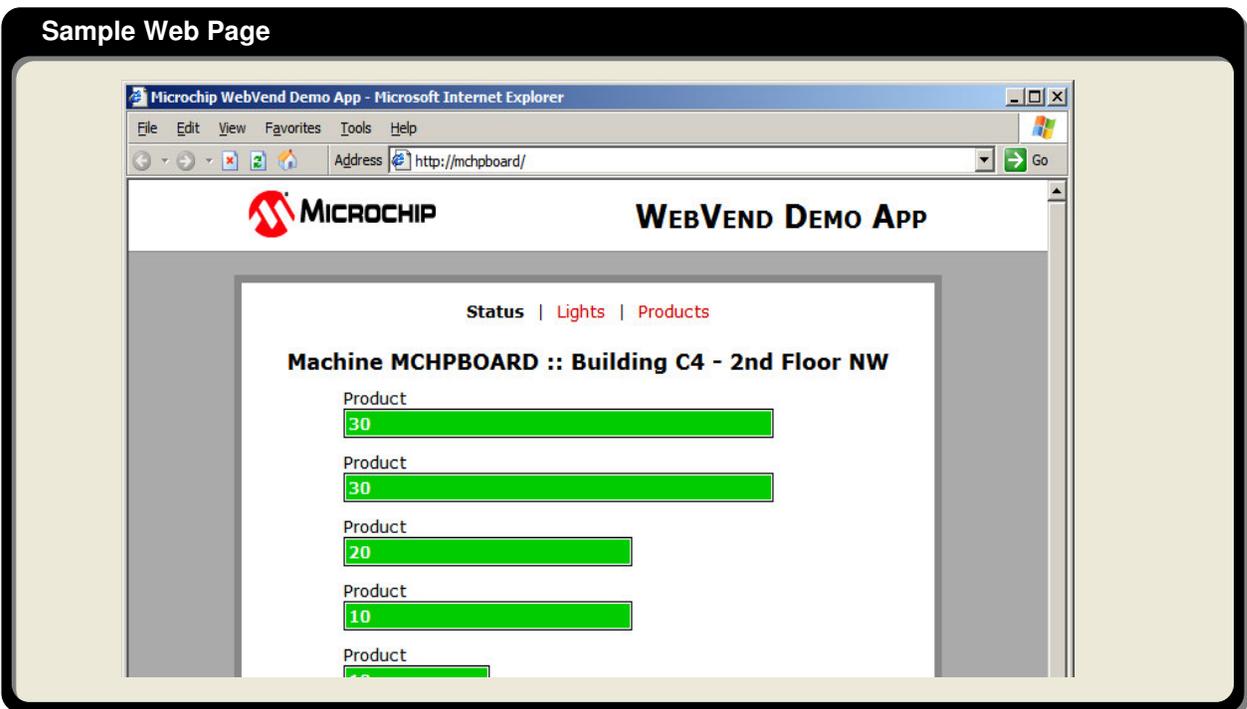
BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

11

Confirm the Router assigns an new IP Address

Verify that the vending machine still operates as discussed in the initial demo.

Verify that the web pages have the dynamic variables have replaced the static values, specifically hostname and location. The string for the location is set in `VendingMachine.c`, and can be modified there if desired.





Web Page Directory (Destination): C:\Masters\1538Lab5\WebPages2

- 12** Return to `index.htm` in **Crimson Editor**.
 Replace each instance of the static string **“Product”** with a dynamic variable with a single parameter. Call this variable `~name(i)~`, where `i` represents an index from 0 to 6. This adds dynamic variables for each of the product names.
- 13** Replace each static instance of stock quantities with a dynamic variable. Name this variable `~stock(i)~`, again with indices from 0 to 6. The stock is listed in two places for each bar. The first prints as text inside the bar, while the second controls the display width of the bar. Be sure to replace both locations, but leave the `em` designation. (The `em` is a standard print measurement.)
Ensure you replace all 7 instances for the product and stock entries.
Save your changes to the HTM file.



Index.htm

```

8<!-- ***Lab5 Step3: Replace "... HOSTNAME" and "... Description" with a dynamic variables "hostname" and "machineDesc" -->
9<div id="location">~hostname~ :: ~machineDesc~ </div>
10
11<!-- ***Lab5 Step12 and 13: Replace each listing of "Product" with a dynamic variable "name" and -->
12<!-- *** static instance quantity with a dynamic variable "stock(i)" where i is 0 thru 6 -->
13
14<!-- ***Lab5 Bonus Step18: Replace each fixed "bar-in..." statement with a the dynamic variable "status(i)" -->
15<!-- *** where i is 0 thru 6 -->
16
17<div id="bargraph">
18
19
20<div class="productname">~name(0)~</div>
21<div class="bar-out" style="width: ~stock(0)~em">
22<div class="bar-in-ok">~stock(0)~</div>
23</div>
24
25<div class="productname">~name(1)~</div>
26<div class="bar-out" style="width: ~stock(1)~em">
27<div class="bar-in-ok">~stock(1)~</div>
28</div>
29
30<div class="productname">~name(2)~</div>
31<div class="bar-out" style="width: ~stock(2)~em">
32<div class="bar-in-ok">~stock(2)~</div>
33</div>
34
35<div class="productname">~name(3)~</div>
36<div class="bar-out" style="width: ~stock(3)~em">
37<div class="bar-in-ok">~stock(3)~</div>
38</div>
39
40<div class="productname">~name(4)~</div>

```

14

Execute **MPFS2 Utility** similar to step 4 and click **Generate and Upload** to program your new web pages.
 . (IF USING THE SOLUTION WORKSPACE, skip to Step 16 to continue)

1538-TCP2

- 15 Insert another callback function `HTTPPrint_name()` into `CustomHTTPApp.c`. to display the name of the requested product. This function accepts a single `WORD` parameter. Product data is stored in the `Products` array. Use the parameter as an index to this array, and print out the associated `name` element using `TCPPutString`, as shown below.
- 16 Insert **another** callback function for `HTTPPrint_stock()`. This function also accepts a single `WORD` parameter. Use the `uitoa(WORD, BYTE*)` function to convert the stock element from a binary value to a string, then write the output to the socket.



CustomHTTPApp.c

```
1407     /
1408         curHTTP.callbackPos = 0x00;
1409         TCPPutString(skthHTTP,machineDesc);
1410     }
1411
1412 void HTTPPrint_name(WORD item)
1413 {
1414     TCPPutString(skthHTTP, Products[item].name);
1415 }
1416
1417 void HTTPPrint_stock(WORD item)
1418 {
1419     BYTE buf[4];
1420
1421     uitoa(Products[item].stock,buf);
1422     TCPPutString(skthHTTP,buf);
1423 }
```

15

16

17



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in RELEASE mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

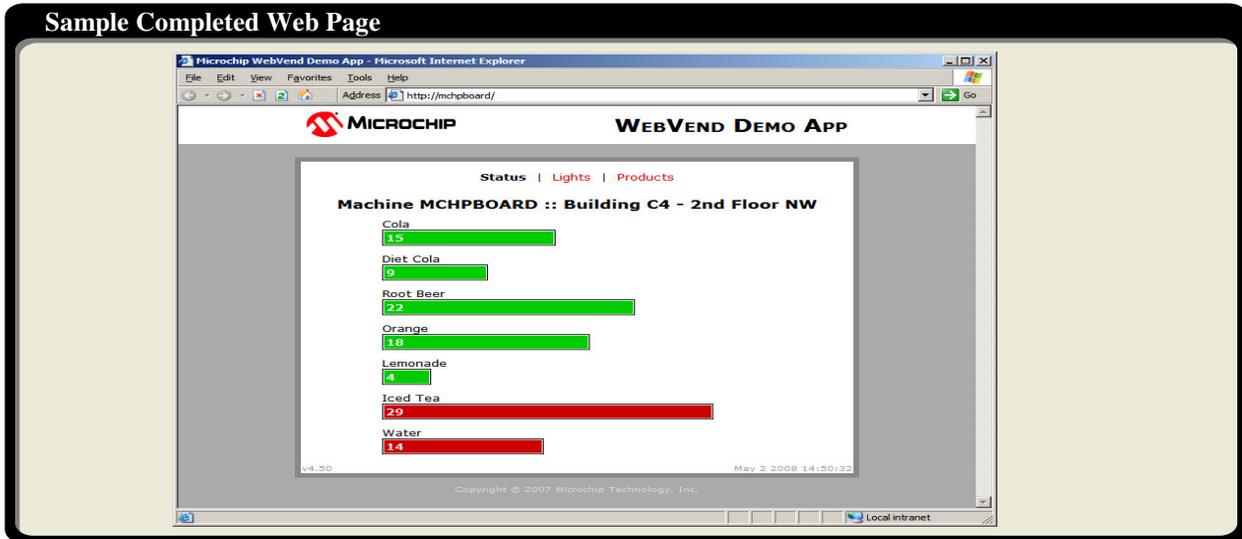
18

Access your board's web page using a web browser. Verify that the bar graph display is now populated with dynamic data from the board. Vend a few drinks and click **Refresh** in your browser to verify that the stock numbers and bar lengths change.



Results A completed implementation will look similar to the following when viewed in a web browser. As products are purchased from the machine, a refresh of the browser page will indicate the new stock levels. An automatically updating display, while technically feasible, is outside the scope of this class.

Sample Completed Web Page



Code Analysis In the HTML file, two types of dynamic callbacks were inserted. In the first portion of the lab, standard text outputs were added. These callbacks receive no parameters, and only needed to call `TCPPutString()` to write text into the web page.

One of these callbacks (for the machine description string) may need to output more than 16 bytes. To prevent potential buffer overruns, this callback had to manage its output state. Since the output was still relatively short, the function just checks if enough space is available. If not, it returns after setting a flag in `curHTTP.callbackPos`, which indicates to the server that this callback must be invoked again to complete its output. This is an acceptable solution for strings less than about 50 bytes. For longer outputs, write as many bytes as possible and use the `callbackPos` variable to track to position of the output, as discussed in the lecture slides. Once complete, restore the `callbackPos` variable to zero to indicate that the callback is finished. Dynamic variables for the names and stock levels of each product were also added. These variables had parameters passed to the functions. All parameters are passed as `WORD` values, which the callback function uses as an index to the `Products` array. The outputs of these functions were used for both printing text and controlling display elements, such as the length of the bars in the graph display.



Conclusions

In this lab, web-based monitoring was added to the vending machine. Several examples of dynamic variables were implemented, demonstrating a wide range of capabilities for this flexible feature. With just a few lines of code, the vending machine can now output its current status in a clean bar graph display.

Bonus Procedure

Dynamic variables can also be used to control visual elements. Notice that one of the bottom two bars are red, while the other bars are green. We'd like to control this color so that any products where stock is running low are automatically highlighted in red.

- 18 Replace the text `class` attributes `low` and `ok` with a dynamic variable called `~status(i)~` within the `index.htm` file via Crimson Editor.
- 19 Execute **MPFS2 Utility** to bundle your changes to the webpage and upload them to the development board. The utility will also update your copy of `HTTPPrint.h` to link in your new dynamic variables.
- 20 Insert a callback for `HTTPPrint_status()` in `CustomHTTPApp.c`. This callback function should print the string "low" if stock is less than 8, and "ok" otherwise.

21



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in **RELEASE** mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

22

Verify after selective vending, the quantities and colors change appropriately.



BONUS index.htm

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```

18

18



CustomHTTPApp.c

20

```

1424
1425 void HTTPPrint_status (WORD item)
1426 {
1427     if (Products[item].stock < 8)
1428         TCPPutROMString (sktHTTP, (ROM BYTE*) "low");
1429     else
1430         TCPPutROMString (sktHTTP, (ROM BYTE*) "ok");
1431 }
1432
1433 #endif
1434

```

Sample Web Page after Bonus Procedure

Microchip WebVend Demo App - Windows Internet Explorer

http://mchpboard/index.htm

File Edit View Favorites Tools Help

Microchip WebVend Demo App

MICROCHIP COM4201 DEMO APP

Status | Lights | Products

MCHPBOARD :: Building C4 - 2nd Floor NW

Cola	13
Diet Cola	7
Root Beer	22
Orange	18
Lemonade	4
Iced Tea	20
Water	14

Copyright © 2007 Microchip Technology, Inc. May 21 2010 11:52:54

Lab Exercise 6

Web-based Control via the GET Method



? Purpose

Now that the vending machine can be monitored remotely, it would be nice to add some control features. As discussed, this can be accomplished through two different HTTP methods: GET and POST.

In this lab, you will learn how to use the GET method to pass short amounts of data to the device. In the process, an interface for controlling the lights on the vending machine will be added. Since the current development platform only has LEDs, one of these will be used for simulation. Control via the POST method will be discussed in a future class.

☑ Requirements

Environment: MPLAB® IDE 8.60 , X, or later, MPFS Utility, Masters 1538 Installer 1.536

C Compiler: MPLAB C18 v3.38 or later, C30 v3.30 or later, or C32 v1.12 or later

H/W Tools: PIC18F: PICDEM.net™ 2, or

PIC24FFJ128GA010 PIM: Explorer 16 w/ 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0 or

PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10Mbps, 10/100Mbps PICtail™ Plus or MRF24WB0

AND MPLAB Real ICE™, or MPLAB ICD 3

AND DHCP Enabled Router (wired or wireless)

Lab Files: C:\Masters\1538\Lab6...

🎯 Objectives

- Study the procedural steps associated with adding HTML forms to a web page to implement control
- Practice with including the necessary Callback code within an application to issue HTML Get based control.



Web Page Directory:

C:\Masters\1538\Lab6\WebPages2



Procedures

1

Open `lights.htm`, from the folder listed above with the Crimson Editor.

This file contains the HTML form that will be used to CONTROL the LEDs.

Start ▶ **Programs** ▶ **Crimson Editor** ▶ **Crimson Editor**

2

Find the `<form>` tag, and notice that the `method` attribute is set to `get`. The form contains two input buttons, both of which are named lights.

Find the radio button inputs. Notice that both are named `lights`. When the form is submitted, the value of the lights parameter will be set equal to whichever radio button is selected.



lights.htm

2

```

16
17 <!-- These two fields create the On/Off radio selectors -->
18 <input type="radio" name="lights" value="1" /> On
19 <input type="radio" name="lights" value="0" /> Off
20

```

3

Execute **MPFS2 Utility** similar to Lab5 step 4 and click **Generate and Upload** to program your new web pages.

(IF USING THE SOLUTION WORKSPACE, skip to Step 8 to continue)

4

MPLAB File ► Open Project



Lab6-C18-PICDN2-ETH97.X for the PICDEM.net 2 with internal MAC/PHY setup

Lab6-C18-PICDN2-MRF24WB.X for the PICDEM.net 2 with Wireless MAC/PHY setup

Lab6-C30-EXP16-ENC28.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10Mbps module

Lab6-C30-EXP16-ENC624.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with 10/100Mbps module

Lab6-C30-EXP16-MRF24WB.X for the Explorer 16 with PIC24F/dsPIC33F PIMs with WIFI module

Lab6-C32-EXP16-ENC28.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10Mbps module

Lab6-C32-EXP16-ENC624.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with 10/100Mbps module

Lab6-C32-EXP16-MRF24WB.X for the Explorer 16 with PIC32MX3xx/4xx PIMs with WIFI module

5

Open **CustomHTTPApp.c** within MPLAB's project window. Forms submitted via GET are processed in **HTTPExecuteGet()**. Find this function.

Note: The first step in this function is to determine which file name is being accessed (and therefore which form has been submitted). The call to **MPFSGetFilename()** handles this, and then a **memcmp** variant is used to check the filename.



memcmppgm2ram() compares an array in RAM to an array in program memory. It accepts the two pointers and a length parameter. If the two arrays match, it returns zero, which is why the comparison is inverted.

6

Update the first comparison to check for **lights.htm**. Remember to update the length parameter to **10** as well. If the name matches, the application should now look for a parameter called **"lights"**. If the pointer returned by the call to **HTTPGetROMArg()** is not **NULL** and matches ASCII **'1'**, the pin **LED4_IO** should be turned on. Otherwise, the pin should be set to off.



Parameters returned from web forms are always represented as strings. If you return numeric values, they must be parsed from their string representations.

- 7 Insert the form processing functionality as shown on the following page. Remove any remaining code in `HTTPExecuteGet()`, which will include the processors for `cookies.htm` and `leds.cgi`. These forms were implemented in the demo application, but no longer exist in your project's web pages. **Ensure** that the function still returns `HTTP_IO_DONE`. This indicates to the HTTP2 server that the function is complete and should not be called again.

CustomHTTPApp.c

```

184 *****/
185 HTTP_IO_RESULT HTTPExecuteGet(void)
186 {
187     BYTE *ptr;
188     BYTE filename[20];
189
190     // Load the file name
191     // Make sure BYTE filename[] above is large enough for your longest name
192     MPFSGetFilename(curHTTP.file, filename, 20);
193
194     // If its the forms.htm page
195     if(!memcmppgm2ram(filename, "lights.htm", 10))
196     {
197         // Seek out each of the four LED strings, and if it exists set the LED states
198         ptr = HTTPGetROMArg(curHTTP.data, (ROM BYTE *)"lights");
199         if(ptr)
200             LED4_IO = (*ptr == '1');
201     }
202     return HTTP_IO_DONE;
203 }
204

```

- 8 **SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS.** Build and Program the firmware into the selected device in **RELEASE** mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

- 9 Access your board's web page and click on the link for **Lights**. Verify that one of the LEDs on the board can be controlled using the web form.



Results

A correct implementation will allow you to control the state of one LEDs using a web form.

Code Analysis



As mentioned earlier, data received via the GET method is stored in `curHTTP.data`. This data is located using `HTTPGetROMArg()`, which returns a pointer to the value, or NULL when the requested parameter was not found. This pointer is then compared against expected values to determine the appropriate action.

Since `HTTPExecuteGet ()` handles all GET forms, the function must resolve the form that was submitted by checking the file name. The `MPFSGetFilename ()` function determines the name of the file being accessed by the server and stores it back to the temporary string for comparison.



Bonus Procedure

Most web forms pre-select the current value to provide a more intuitive interface to the user. This can be accomplished for your form using dynamic variables.

10

Open `lights.htm` in **Crimson Editor** again. You will add a dynamic variable here to pre-select the correct radio button depending on whether the LED is on or off. A radio button will be selected if it has a `checked` attribute.

11

Insert a dynamic variable in each radio button, which will allow your application to dynamically insert this attribute.

Save your changes to the HTML code

12

Execute **MPFS2 Utility** similar to step 3 and click **Generate and Upload** to program your new web pages. (IF USING THE SOLUTION WORKSPACE, skip to Step 15 to continue)



lights.htm

11

```

16
17 <!-- These two fields create the On/Off radio selectors -->
18 <input type="radio" name="lights" value="1" ~light_chk(1)~ /> On
19 <input type="radio" name="lights" value="0" ~light_chk(0)~ /> Off
20

```

13

Insert the callback function `HTTPPrint_light_chk ()` via MPLAB into the file `CustomHTTPApp.c`. This function will accept a single `WORD` parameter.



CustomHTTPApp.c

13

```

1374 }
1375
1376 void HTTPPrint_light_chk(WORD state)
1377 {
1378     if(state == LED4_IO)
1379         TCPPutROMString(sktHTTP, (ROM BYTE*)"checked");
1380 }
1381 #endif

```

14

1538-TCP2

14

Inside this function, Insert a check if the parameter received matches the current state of `LED4_IO`. If it does, use `TCPPutROMString()` to write the string "checked" to the page.

15



SEE THE SECTION 2.1 OR 2.3 OF APPENDIX A FOR MPLABX BUILD AND/OR RUN OPTIONS. Build and Program the firmware into the selected device in `RELEASE` mode.



BUILD TO CONFIRM NO SYNTAX ERRORS



SEE SECTION 1.8 IN APPENDIX A FOR CONFIGURING YOUR PROGRAMMER



BUILD, PROGRAM AND RUN IN THE TARGET SYSTEM

16

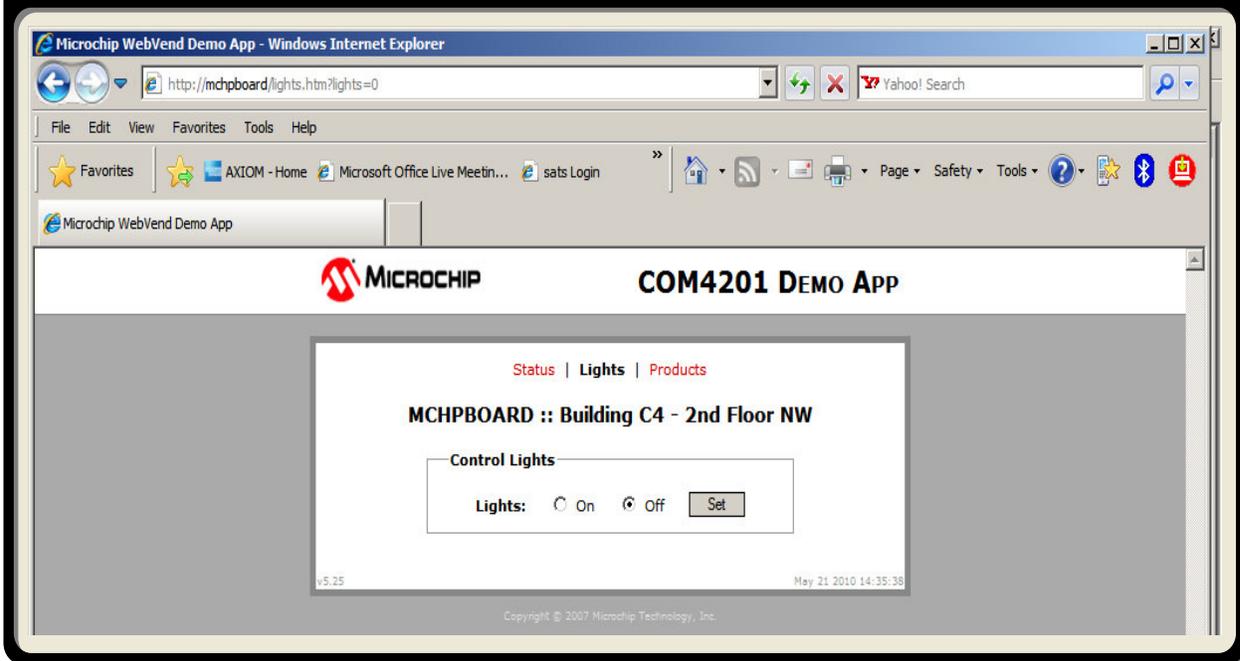
Verify that the current state of the LED is now pre-selected on your form when the page loads.



Bonus Procedure Results:

In this section, a dynamic variable was added to the radio buttons. This dynamic variable either prints "checked" or nothing, depending on the state of the LED. By printing "checked", the server can control the default state of

Pre-Selected Radio Button



Appendix A

MPLAB[®] X IDE Quick Reference Guide



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Section 1.7 How to close a project

- There are two methods you can use to close a project:

Method 1:
Right click on the top node of the project in the project tree (the chip icon) and select **Close** from the popup menu (about 2/3 of the way down).

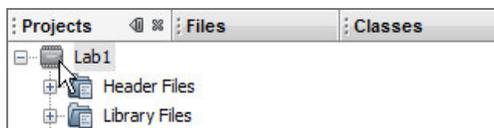
Method 2:
From the main menu, select **File ▶ Close Project (project name)** where *project name* is the name of the project you wish to close—there may be multiple similar menu items if you have more than one project open in the IDE.

Section 1.8 How to modify project settings

- There are three ways to access a project’s settings:

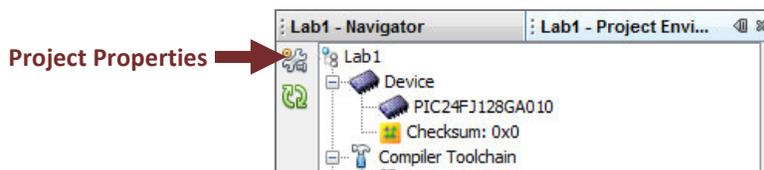
Method 1:
Right click on the top node (chip icon) of a project in the project tree and select **Properties** at the very bottom of the long popup menu.

Figure 1.8.1
The top node of a project in the project tree

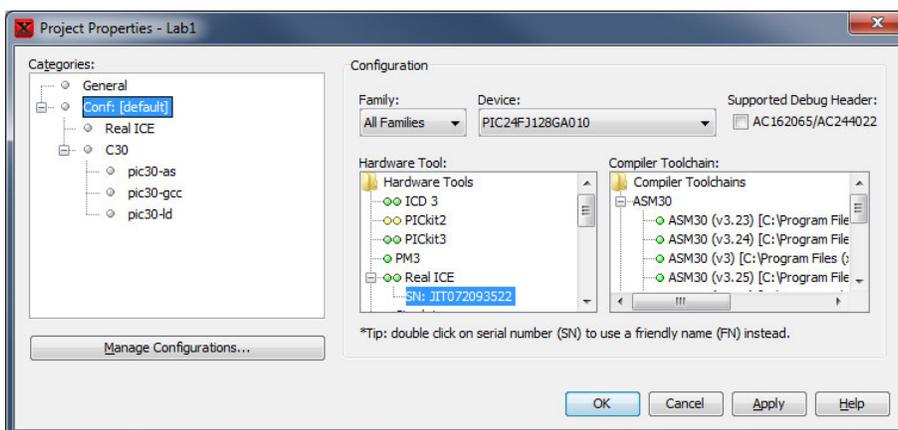


- Method 2:**
From the main menu select **File ▶ Project Properties (project name)**
- Method 3:**
If the **Project Environment** window is open (bottom left corner by default), you can click on the “wrench and bolt” icon in its left margin.

Figure 1.8.2
Project Properties button in the Project Environment window.



- From here you can select a different device, debug tool or build tool and you can modify any of their settings. When choosing a new tool, click the Apply button to make it show up in the tree on the left side.



2. Building Projects



Section 2.1

How to build a project

There are several ways to build a project in MPLAB X depending on what you intend to do with the results. This method is only used to see the results of a build or to produce a release mode hex file.

There are two different types of build you can do:

Build:

This will build only the files in your project that have changed since the last build or it will build everything if nothing has been built previously. It will generally be faster to use this type of build, especially for larger projects.

Clean and Build:

This will remove any intermediate files generated by the previous build and will build every file in your project regardless of whether or not it has changed since the last build to ensure a full, clean build.

- 1 There are two ways to access these two build types:
From the Main Toolbar:



Build

Make in MPLAB IDE 8



Clean and Build

Build All in MPLAB IDE 8

Alternatively, you can right click on the top node of a project (chip icon) in the project tree and select either **Build** or **Clean and Build** from the popup menu.



Information

The **Build** and **Clean and Build** functions are not intended for use before **Run Project**, **Debug Project** or **Make and Program Target**. All three of those functions automatically do a build before performing further steps. No harm will be done by using **Build** or **Clean and Build** first, but it will be a duplication of effort and will waste time.



Section 2.2

How to build and run a project with a debugger

When you want to build a project for the purpose of programming a target to run with a debugger like the MPLAB® ICD 3 or REAL ICE, this is the method to use.

- 1 There are three ways to build and run your code through a debugger:

Method 1:

Click on the **Debug Project** button on the main toolbar 

Method 2:

Right click on the top node of the project (chip icon) in the project tree and select **Debug** from the popup menu.

Method 3:

From the main menu, select **Debug** ▶ **Debug Project (project name)**

This will perform the following tasks automatically:

- a. Build (make) project in debug mode
- b. Program target (unless using simulator)
- c. Run code on target



Information

It is not necessary to do a **Build** or **Clean and Build** before doing a **Debug Project** because a build will be done automatically.



Section 2.3

How to build and run a project without a debugger



Information

It is not necessary to do a **Build** or **Clean and Build** before doing a **Run Project** because a build will be done automatically.

When you want to build a project for the purpose of programming a target to run without a debugger, this is the method to use.



There are three ways to build and run your code on a target:

Method 1:

Click on the **Run Project** button on the main toolbar 

Method 2:

Right click on the top node of the project (chip icon) in the project tree and select **Run** from the popup menu.

Method 3:

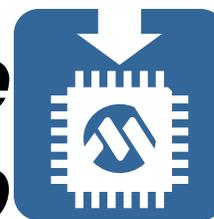
From the main menu, select **Run ▶ Run Project (*project name*)**

This will perform the following tasks automatically:

- a. Build (make) project in release mode
- b. Program target
- c. Run code on target

Additional Exercise

Creating a Simple Web



Purpose

Modern web pages are created using a combination of HTML and CSS code. HTML is a markup language, meaning that the content is divided into a structure, with each element given a specific type. CSS is a style language which specifies how to present the content found in the HTML structure. Together, these files are parsed by a web browser to create the on-screen display.

In this lab, you will create a simple web page with your name, a brief paragraph about yourself, and a few visual elements. You will test your page using the web browser on your PC.

Web pages for Microchip's embedded platforms are compiled into an Microchip File System (MPFS) image. This image is similar to a zip file, and includes all of your web page code in a format that is easy for the PIC to serve. To finish the lab, you will bundle and upload your web page to your development board using the **MPFS2 Utility**, which will allow other attendees to view the page on their PC.

If you finish early, a bonus section will teach some basic CSS to help you format your page.

Requirements

Software: MPFS utility from Masters 1538 Installer v1.536, Crimson Editor
Environment: MPLAB[®] IDE 8.60 ,X, or later, Masters 1538 Installer 1.536
C Compiler: Not Required for this Lab
H/W Tools: PIC18F: PICDEM.net[™] 2, or
 PIC24FFJ128GA010 PIM: Explorer 16 w/ 10Mbps, 10/100Mbps PICtail[™] Plus or MRF24WB0 or
 PIC32MX360 or PIC32MX460 PIM: Explorer 16 & 10Mbps, 10/100Mbps PICtail[™] Plus or MRF24WB0
 AND MPLAB Real ICE[™], or MPLAB ICD 3
 AND DHCP Enabled Router (wired or wireless)
Lab Files: C:\Masters\1538\AddlLab\...

Objectives

- Practice HTML and CSS style sheet programming
- Utilize the MPFS utility to package web page information and transfer to dev tools via TCP/IP



Web Page Directory: C:\Masters\1538\AddlLab\WebPages2

Procedures

- 1** **Confirm** all the files located in WebPages2 directory shown above are deleted. These are shipped with the TCP/IP Stack, but are not needed for this class. However the same folder location will be used for new pages.

Appendix A

2

Launch the **Crimson Editor** to create a new file named `index.htm` and save it in the **WebPages2** mentioned previously. **Start ▶ Programs ▶ Crimson Editor ▶ Crimson Editor File ▶ New File ▶ Save As ▶ index.htm** in the folder `C:\Masters\1538\Add1Lab\Webpages2\`



The default extension for HTML code in Crimson Editor is `*.html`. The default file name for the HTTP2 server is `index.htm`. Make sure your extension only has three letters!

3

Insert the required `<html>`, `<head>`, and `<body>` structure tags as shown in the sample web page below. **Include** the appropriate closing tags `</html>`, `</head>`, and `</body>` as well.



Sample HTML Page Structure

```
<html>
  <head>
    <title>My First Web Page</title>
  </head>
  <body>
    <h1>My First Web Page</h1>
    <p>Compared to assembly, HTML is <b>really</b> easy!</p>
  </body>
</html>
```

4

Inside the `<head>` tag, insert a `<title>` tag enclosing your company name. Insert a `<h1>` tag inside the `<body>` tag, enclosing your personal name. Be sure to **include** appropriate closing tags as well.

5

Below the `<h1>` tag, insert a `<p>` tag enclosing two brief sentences about yourself. This will appear as a paragraph of text on your page.

Below the `<p>` tag, insert another `<p>` tag. **List** information from your business card such as your name, title, address, and phone number. Insert a `
` tag to add a line break after each element of data.

6



In HTML, a `<title>` tag in the `<head>` section displays in the browser's title bar, but not on the page itself. The `<h1>` tag will display as big bold text in your page. `<p>` tags are displayed with a blank line of space between them.

The `
` tag forces a line break without this extra line of space. The `
` tag is a self-closing tag. It does not enclose content, but merely indicates a visual display element. Other examples of self-closing tags include image tags `` and form input fields `<input ... />`.

7

Insert a link to your company's website (or a site of your choosing) as the last line in the "business card" information. Use an `<a>` tag. Insert an `href` (hyper-text reference) parameter to the tag indicating the link's destination. Enclose the text you wish to display (underlined in blue) in between the `<a>` and `` tags. It should look something like:

```
<a href="http://www.microchip.com">www.microchip.com</a>
```



This should be a fully qualified URL, including `http://`, because the link references an external server. For local links you would list only the relative path to the page, such as:

```
<a href="page2.htm">Next Page</a>
```

8

Save the file, then view your completed web page by opening it in your web browser.

Windows Desktop ▶ **My Computer** ▶ **Navigate to WebPages2** ▶ **Double Click index.htm**



As you view the web page in the step, you can return to steps 3 through 8 to make changes. After saving, use the browser's **Refresh** button to see the modifications.



Note the size of the file as it is saved from Crimson Editor, less than 500 bytes. It is important to avoid using editors that generate large files that become difficult to fit in embedded memory arrays.

Sample Web Page

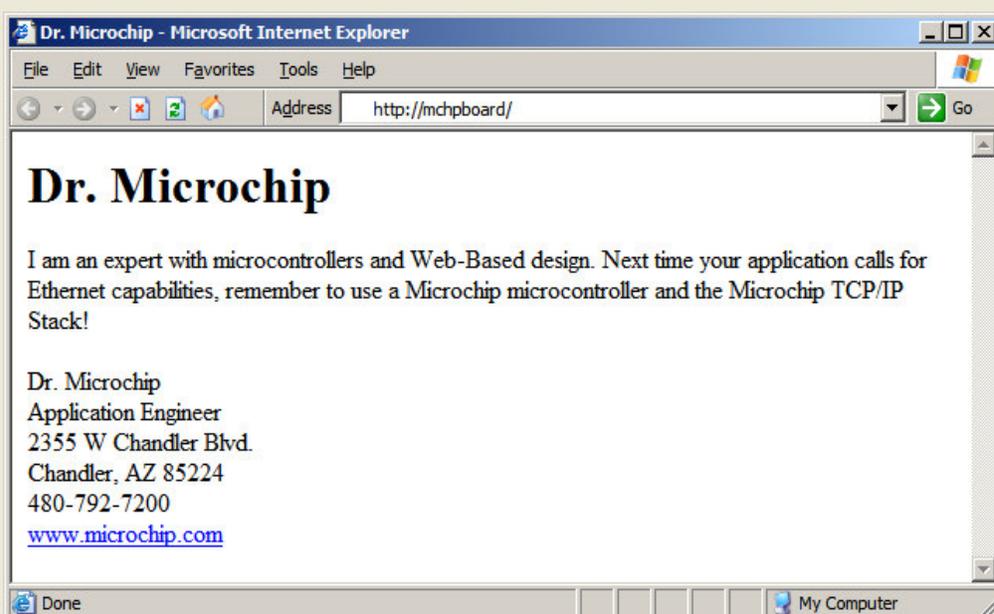
4

4

5

6

7



Your classroom may not have Internet access, so the link you added to your web page may not work properly.

Appendix A



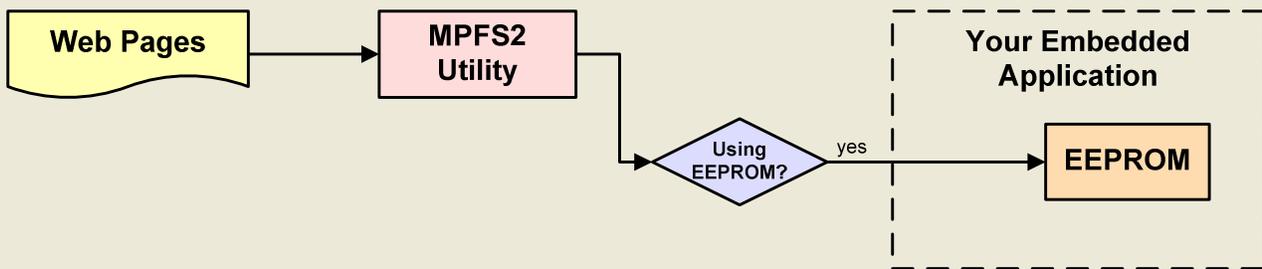
In the next few steps, you will use the MPFS2 Utility to bundle your web page and upload it to your development board. Before beginning, ensure that your development board is still running by confirming the new IP address on the LCD, and confirm the index.htm is saved.

9

Open the **MPFS2 Utility**, so on the next page of this manual.
[Start](#) ▶ [Programs](#) ▶ [Microchip](#) ▶ [1538](#) ▶ [MPFS2](#)



How Web Pages are Bundled



Source Directory:

C:\Masters\1538\AddLab\WebPages2

10

Confirm that **Start With: Webpage Directory** is selected and that the correct source directory shown above is entered:

11

Confirm that **Output: BIN Image** is selected.



Project Directory:

C:\Masters\1538\AddLab

12

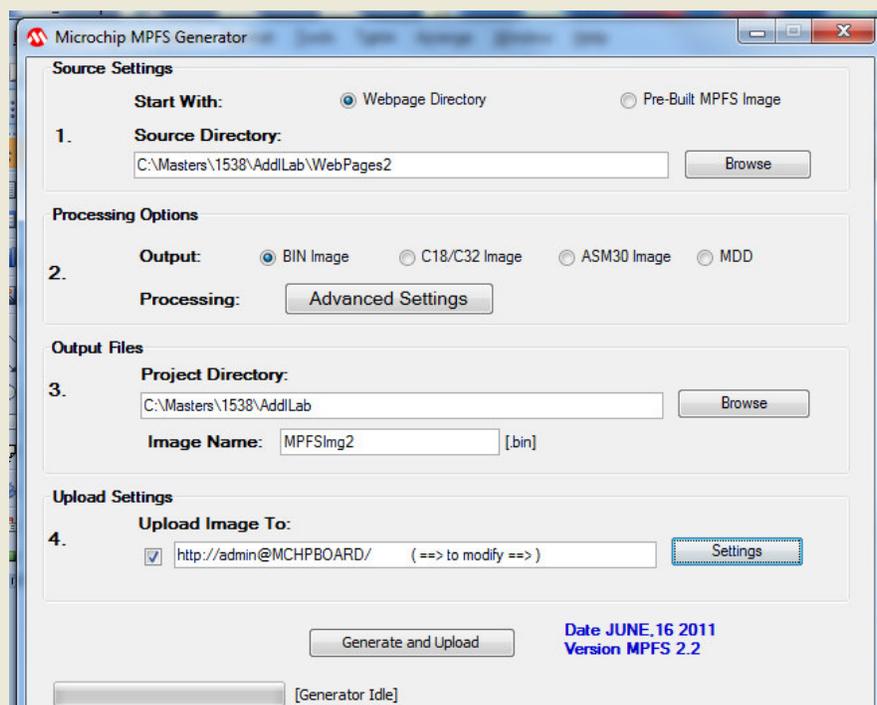
Confirm that the **OUTPUT FILES** project directory shown above is entered:

13

Confirm that **Upload Image** is selected. Then click the **Settings** button and make the following changes and confirmations:

- Click the **Defaults** button to restore the standard settings.
- Set the **Device Address** to the host name you chose in Lab 1.
- Click **OK** to save your changes.

MPFS2 Utility After Configuration



The next step may cause the Windows Firewall to prompt you about allowing the MPFS Generator to access the network. Be sure to click **Unblock** if this occurs.

14

Click the **Generate and Upload** button. The MPFS2 Utility will package your web page and upload it to the development board.

The MPFS2 Utility

15

Verify that you can now access your new web page from your board using the same address as you used in Lab 1. Ensure the ICD2 debugger is disconnected and Confirm the Router has assigned an IP Address.

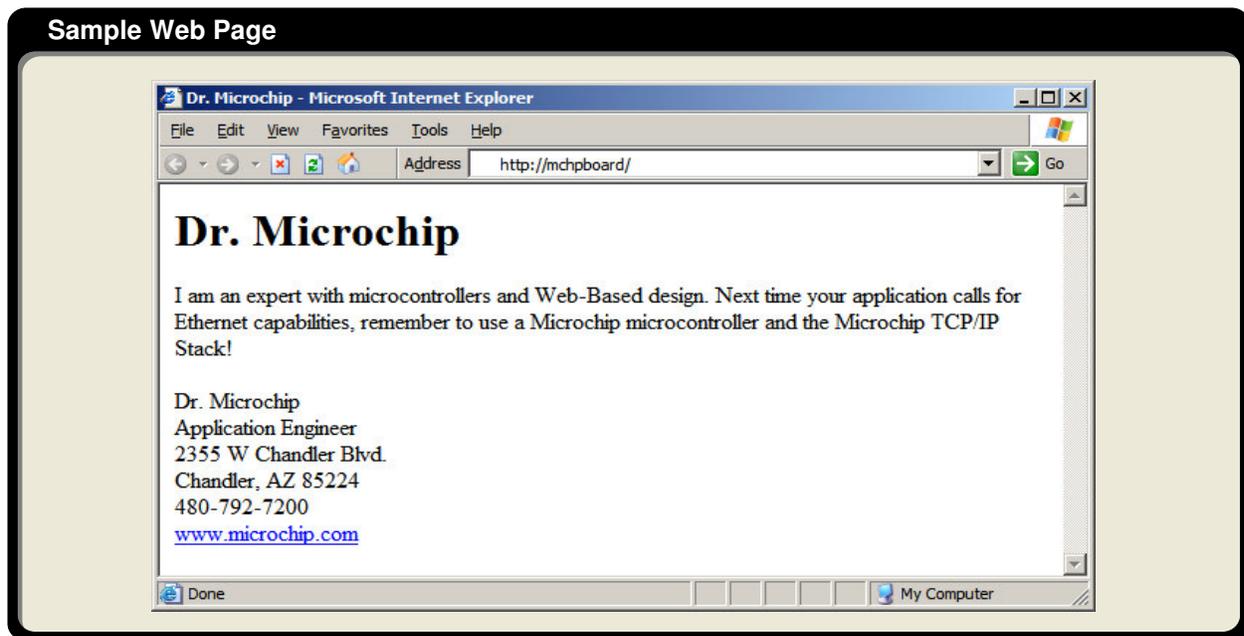
16

Access your neighbor's board using their host name in your browser's address bar. also access your web page from their browser.

Confirm that they can



Results



Bonus Procedure

17

Return to `index.htm` in **Crimson Editor**. Insert a link to the style sheet you will create within the `<head>` section:

```
<link href="style.css" rel="stylesheet" type="text/css" />
```

18

Insert a `class` parameter to the opening `<p>` tag containing your business card information. (The closing tag does not need modification.) The opening tag should now look like:

```
<p class="businesscard">
```

19

Save the newly modified `index.htm`,
File ▶ **Save**

20

Create a new file named `style.css` and save it in the **WebPages2** folder with your HTML page.
File ▶ **New File** ▶ **Save As** ▶ `style.css`

21

Insert style sections to the file as shown in the code analysis section on the following page. Save your changes, then repeat steps 14 and 15 to verify that your changes are visible.



Colors are represented as hex RGB triplets, and you may modify them as you like. Sections matching the name of a tag apply to all tags of that type. Sections with a period separator followed by another name apply only to tags with a class matching the second name.



Bonus Results

Final Web Page



Code Analysis



index.htm

```

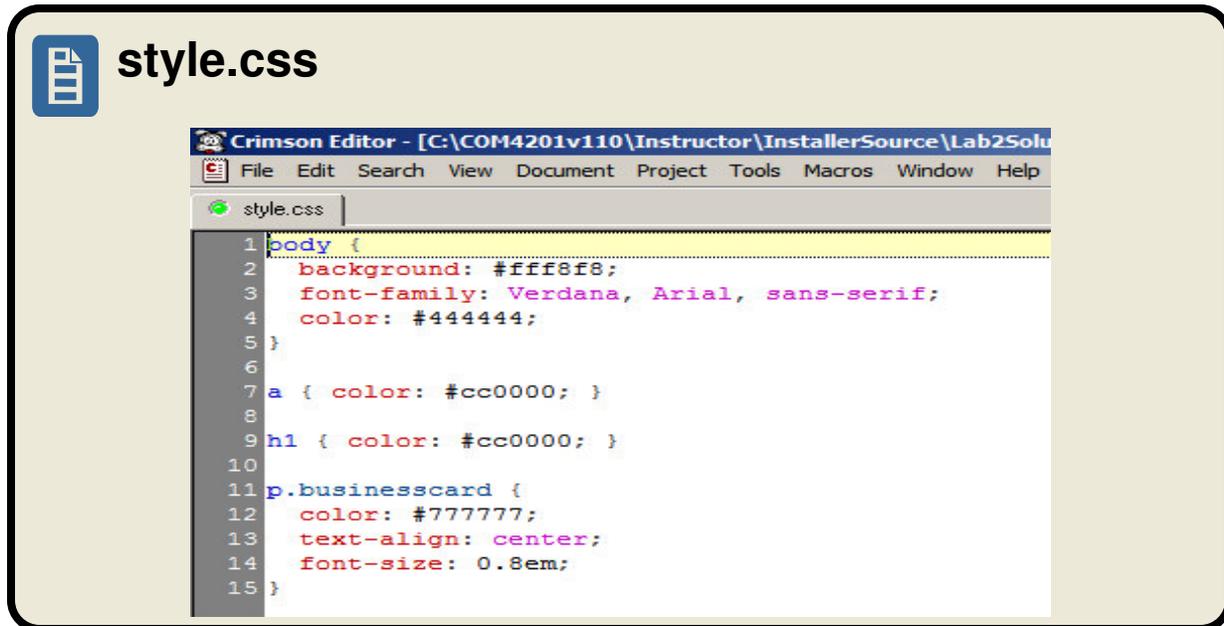
1 <html>
2   <head>
3     <title>Dr. Microchip</title>
4     <link href="style.css" rel="stylesheet" type="text/css" />
5   </head>
6   <body>
7     <h1>Dr. Microchip</h1>
8     <p>I am an expert with microcontrollers and Web-Based design. Next
9     time your application calls for Ethernet capabilities, remember
10    to use a Microchip microcontroller and the Microchip TCP/IP Stack!</p>
11    <p class="businesscard">
12      Dr. Microchip<br />
13      Application Engineer<br />
14      2355 W Chandler Blvd.<br />
15      Chandler, AZ 85224<br />
16      480-792-7200<br />
17      <a href="http://www.microchip.com">www.microchip.com</a></p>
18    </body>
19 </html>

```

The HTML document follows the required structure with an `<html>` tag enclosing `<head>` and `<body>` tags. The `<title>` tag is added to give the page a title in the browser's title bar (as well as in search engines, bookmarks, and other locations).

Appendix A

Within the body section, a header is inserted, followed by two paragraphs. The second paragraph uses the line break tag to force new lines. Each tag (except for self-closing tags) has an associated closing tag terminating each section. The `<link>` tag will only exist in your HTML if you completed the bonus section, as will the `class` attribute in the second `<p>` tag. If you did finish this section, you will also have a `style.css` file that looks similar to the following:



The image shows a screenshot of a text editor window titled "Crimson Editor - [C:\COM4201v110\Instructor\InstallerSource\Lab2Solu". The editor is displaying the contents of a file named "style.css". The code is as follows:

```
1 body {
2   background: #fff8f8;
3   font-family: Verdana, Arial, sans-serif;
4   color: #444444;
5 }
6
7 a { color: #cc0000; }
8
9 h1 { color: #cc0000; }
10
11 p.businesscard {
12   color: #777777;
13   text-align: center;
14   font-size: 0.8em;
15 }
```

Conclusion

This lab has presented an extremely brief overview of HTML and CSS. These languages form the foundation for modern web page development. Before starting your own designs, you'll want to read about the other capabilities of HTML, including `<form>` tags, ``, `<div>`, ``, and in-line formatting with `` and `<i>`.

HTML and CSS are well documented in recommendations posted by the World Wide Web Consortium at their website, www.w3c.org. For those who prefer tutorials to dense technical specifications, a quick visit to your favorite search engine will turn up hundreds of sites teaching the fundamentals of HTML design.

For the remainder of the class, you will only need to be able to read and understand the structure of a few HTML documents. The web pages used for this class will be provided, so you will not need to build them from scratch. This purpose of this exercise is only to familiarize yourself with HTML and learn enough to read code later.